



Research Article

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Set-theoretic solutions to the Yang–Baxter equation and generalized semi-braces

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Abstract: This paper aims to introduce a construction technique of set-theoretic solutions of the Yang–Baxter equation, called *strong semilattice of solutions*. This technique, inspired by the strong semilattice of semi-groups, allows one to obtain new solutions. In particular, this method turns out to be useful to provide non-bijective solutions of finite order. It is well-known that braces, skew braces and semi-braces are closely linked with solutions. Hence, we introduce a generalization of the algebraic structure of semi-braces based on this new construction technique of solutions.

Keywords: Quantum Yang–Baxter equation, set-theoretical solution, brace, skew brace, semi-brace, generalized semi-brace

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1 Introduction

The quantum Yang–Baxter equation appeared in the work of Yang [49] and Baxter [2]. It is one of the basic equations in mathematical physics, and it laid the foundations of the theory of quantum groups [33]. Solutions of the Yang–Baxter equation are instrumental in the construction of semisimple Hopf algebras [23, 43] and provide examples of coloring invariants in knot theory [41]. More recently, the Yang–Baxter solution popped up in the theory of quantum computation [34, 50], where solutions of the Yang–Baxter equation provide so-called universal gates. One of the central open problems is to find all solutions of the Yang–Baxter equation. Let V be a vector space over a field K . Then a solution of the Yang–Baxter equation is a linear map $R : V \otimes V \rightarrow V \otimes V$ for which the following holds on $V^{\otimes 3}$:

$$(R \otimes \text{id}_V)(\text{id}_V \otimes R)(R \otimes \text{id}_V) = (\text{id}_V \otimes R)(R \otimes \text{id}_V)(\text{id}_V \otimes R).$$

The simplest solutions are the solutions R induced by a linear extension of a mapping $r : X \times X \rightarrow X \times X$, where X is a basis for V , satisfying the set-theoretic version of the Yang–Baxter equation, i.e., satisfying the following on X^3 :

$$(r \times \text{id}_X)(\text{id}_X \times r)(r \times \text{id}_X) = (\text{id}_X \times r)(r \times \text{id}_X)(\text{id}_X \times r).$$

In this case, r is said to be a *set-theoretic solution of the Yang–Baxter equation* (briefly, a *solution*). Drinfel'd, in [22], posed the question of finding these set-theoretic solutions. Denote for $x, y \in X$ the element

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$r(x, y) = (\lambda_x(y), \rho_y(x))$. One says that a set-theoretic solution r is *left non-degenerate* if λ_x is bijective for every $x \in S$, *right non-degenerate* if ρ_y is bijective for every $y \in S$, and *non-degenerate* if r is both left and right non-degenerate. If a solution is neither left nor right non-degenerate, then it is called *degenerate*. The first papers on set-theoretic solutions are those of Etingof, Schedler and Soloviev [24] and Gateva-Ivanova and Van den Bergh [27]. Both papers considered *involutive* solutions, i.e., solutions r where $r^2 = \text{id}$. Rump [44] introduced a new algebraic structure, braces, that generalizes radical rings and provides an algebraic framework. We provide the equivalent definition formulated by Cedó, Jespers and Okniński [12]. A triple $(B, +, \circ)$ is called a *left brace* if $(B, +)$ is an abelian group and (B, \circ) is a group such that for any $a, b, c \in B$ it holds that

$$a \circ (b + c) = a \circ b - a + a \circ c. \quad (\diamond)$$

This new structure showed connections between the Yang–Baxter equation and ring theory, flat manifolds, orderability of groups, Garside theory, and regular subgroups of the affine group; see, for instance, [5, 6, 14, 15, 21, 25, 46]. Lu, Yan, and Zhu [38] and Soloviev [47] started the study of non-degenerate bijective solutions, not necessarily involutive. Almost all of the ideas used in the theory of involutive solutions can be transported to non-involutive solutions. We also mention Gateva-Ivanova and Majid [26] who studied and characterized most general set-theoretic solutions (braided sets) (X, r) in terms of the induced left and right actions of X on itself, and in terms of abstract matched pair properties of the associated braided monoid $S(X, r)$. The algebraic framework now is provided by skew left braces [28]. Let $(B, +)$ and (B, \circ) be groups on the same set B . If, for any $a, b, c \in B$, condition (\diamond) holds, the triple $(B, +, \circ)$ is called a *skew left brace*. Skew left braces and some of their applications are intensively studied; see, for instance, [8, 13, 20, 35, 45].

In [37], Lebed drew the attention on idempotent solutions. Indeed, using idempotent solutions and graphical calculus from knot theory, she provides a unifying tool to deal with several diverse algebraic structures such as free monoids, free commutative monoids, factorizable monoids, plactic monoids and distributive lattice. Examples and classifications of these solutions have been provided by Matsumoto and Shimizu [39] and by Stanovský and Vojtěchovský [48]. Moreover, Cvetko-Vah and Verwimp [19] provided cubic solutions with skew lattices. A cubic solution r is a solution such that $r^3 = r$; hence, this class includes both involutive and idempotent solutions. More generally, a more systematic approach to the study of solutions with finite order can be found in the recent [9–11]. Catino, Colazzo, and Stefanelli [7] and Jespers and Van Antwerpen [32] introduced the algebraic structure called *left semi-brace* to deal with solutions that are not necessarily non-degenerate or that are idempotent. Let $(B, +)$ be a semigroup and let (B, \circ) be a group. Then $(B, +, \circ)$ is called a left semi-brace if, for any $a, b, c \in B$, it holds that

$$a \circ (b + c) = a \circ b + a \circ (a^- + c),$$

where a^- denotes the inverse a in (B, \circ) . If $(B, +)$ is a left cancellative semigroup, then we call $(B, +, \circ)$ a left cancellative left semi-brace. This was the original definition by Catino, Colazzo and Stefanelli [7]. It has been shown that left semi-braces, under some mild assumption, provide set-theoretic solutions of the Yang–Baxter equation. Moreover, the associated solution is left non-degenerate if and only if the left semi-brace is left cancellative.

Out of algebraic interest, Brzeziński introduced left trusses [4] and left semi-trusses [3]. A quadruple $(B, +, \circ, \lambda)$ is called a *left semi-truss* if both $(B, +)$ and (B, \circ) are semigroups and $\lambda : B \times B \rightarrow B$ is a map such that $a \circ (b + c) = (a \circ b) + \lambda(a, c)$. Clearly, the class of left semi-trusses contains all left semi-braces, rings, associative algebras and distributive lattices. This entails that it will prove difficult to present deep results on this class. However, one may examine large subclasses. In particular, Brzeziński [4] focused on left semi-trusses with a left cancellative semigroup $(B, +)$ and a group (B, \circ) , and showed that such a left semi-truss is equivalent with a left cancellative semi-brace, and thus providing set-theoretic solutions of the Yang–Baxter equation, albeit known ones. In [40], Miccoli introduced almost left semi-braces, a particular instance of left semi-trusses, and constructed set-theoretic solutions associated with this algebraic structure. In [18], Colazzo and Van Antwerpen continued this study focusing on the subclass of brace-like left semi-trusses, i.e., left semi-trusses in which the multiplicative semigroup is a group and which includes almost left semi-braces. Concerning solutions, they showed that the solution one can associate with an almost left semi-brace

is already the associated solution of a left semi-brace. In particular, this shows that brace-like left semi-trusses will not yield a universal algebraic structure that produces set-theoretic solutions.

In this paper, we focus on a new algebraic structure that includes left semi-braces and is an instance of left semi-trusses, which is on a different path with respect to brace-like left semi-trusses, called generalized left semi-brace. A triple $(S, +, \circ)$ is called a *generalized left semi-brace* if $(S, +)$ is a semigroup, (S, \circ) is a completely regular semigroup (or union of groups), and such that, for any $a, b, c \in S$, it holds

$$a \circ (b + c) = a \circ b + a \circ (a^- + c),$$

where a^- denotes the (group) inverse of a in (B, \circ) . We prove that, under some mild assumptions, generalized left semi-braces provide solutions. In particular, elementary examples of generalized left semi-braces produce cubic solutions that cannot be obtained by skew lattices and left semi-braces. Also, we introduce a construction technique that provides generalized left semi-braces called the strong semilattice of generalized left semi-braces. This technique is inspired by the description of semigroups which are unions of groups due to Clifford [16].

Furthermore, we introduce a construction technique for solutions called the strong semilattice of solutions. This technique takes a family of disjoint sets $\{X_\alpha \mid \alpha \in Y\}$ indexed by a semilattice Y and solutions defined on these sets. Then, under some assumptions of compatibility, it allows one to construct a solution on the union of the sets X_α . We prove that the solutions provided by the strong semilattice of left semi-braces are a particular instance of a strong semilattice of solutions.

Finally, we prove that the strong semilattice of solutions is a useful tool to provide solutions of finite order. Indeed, the strong semilattice of solutions of finite order is a solution of finite order. Moreover, a solution r is of finite order if there exist a non-negative integer i and a positive integer p such that $r^{p+i} = r^i$, and the minimal integers that satisfy such relation are said to be index and period, respectively. We show that it is possible to determine the index and the period of the semilattice of solutions $\{r_\alpha \mid \alpha \in Y\}$ as a function of the indexes and periods of r_α . As a corollary of this result, we prove that solutions associated with strong semilattices of left semi-braces are not bijective, so they are clearly different from solutions obtained by left semi-braces.

2 Basic tools on left semi-braces

Let us briefly present some basic background information regarding left semi-braces. Most of the content of this section appears in [32]. In particular, we provide a different proof of [32, Corollary 2.9] based on a result in semigroup theory due to Hickey [29] that gives a clear description of completely regular semigroups with middle units. Moreover, we add further information on the behavior of middle units of the additive semigroup of a left semi-brace. Finally, we present concrete examples of left semi-braces.

Let us start by recalling the definition of left semi-braces.

Definition 2.1. Let B be a set with two operations $+$ and \circ such that $(B, +)$ is a semigroup and (B, \circ) is a group. Then $(B, +, \circ)$ is said to be a *left semi-brace* if

$$a \circ (b + c) = a \circ b + a \circ (a^- + c)$$

for all $a, b, c \in B$, where a^- is the inverse of a in (B, \circ) .

Throughout, 0 denotes the identity of the group (B, \circ) . Moreover, we call $(B, +)$ and (B, \circ) the *additive semigroup* and the *multiplicative group* of the left semi-brace $(B, +, \circ)$, respectively. Furthermore, if the semigroup $(B, +)$ has a pre-fix, pertaining to some property of the semigroup, we will also use this pre-fix with the left semi-brace. Hence, the left semi-braces introduced in [7], where one works under the restriction that the semigroup $(B, +)$ is left cancellative, will be called left cancellative left semi-braces.

Now, we recall that an element u of an arbitrary semigroup $(S, +)$ is a *middle unit* of S if $a + u + b = a + b$ for all $a, b \in S$. Thus, $u + u$ is idempotent, but u itself need not be idempotent (see [17, p. 98]). This is not the case for the element 0 in the additive semigroup of a left semi-brace: the following proposition shows that 0 is an idempotent middle unit.

Proposition 2.2. *Let B be a left semi-brace. Then the following assertions hold:*

- (i) 0 is a middle unit of $(B, +)$.
- (ii) 0 is an idempotent of $(B, +)$.
- (iii) $B = B + B$.
- (iv) $B + 0$ is a subgroup of (B, \circ) .
- (v) $0 + B$ is a subsemigroup of (B, \circ) .

Proof. (i) See [32, Lemma 2.4 (1)].

(ii) Since, by (i), $0 + 0 + 0 = 0 + 0$, we have that

$$\begin{aligned} 0 &= (0 + 0)^- \circ (0 + 0) \\ &= (0 + 0)^- \circ 0 + (0 + 0)^- \circ (0 + 0 + 0) \\ &= (0 + 0)^- + (0 + 0)^- \circ (0 + 0) \\ &= (0 + 0)^- + 0. \end{aligned}$$

Thus, since 0 is a middle unit, we obtain

$$0 + 0 = (0 + 0)^- + 0 + 0 = (0 + 0)^- + 0 = 0.$$

(iii) If $b \in B$, by (ii) we have that

$$b = b \circ 0 = b \circ (0 + 0) = b \circ 0 + b \circ (b^- + 0) \in B + B.$$

(iv) By (ii), it is clear that $B + 0$ is not empty. Moreover, if $a, b \in B$ then, using (i), we get the equalities

$$\begin{aligned} (a + 0)^- \circ (b + 0) &= (a + 0)^- \circ b + (a + 0)^- \circ (a + 0 + 0) \\ &= (a + 0)^- \circ b + (a + 0)^- \circ (a + 0) \\ &= (a + 0)^- \circ b + 0 \in B + 0. \end{aligned}$$

(v) See [32, Lemma 2.6 (iii)]. □

To show the following theorem, let us recall that an arbitrary semigroup $(S, +)$ is said to be a *rectangular group* if it is isomorphic to the direct product of a group and a rectangular band. For more background and details on this topic, we refer the reader to [17].

Theorem 2.3. *Let B be a completely simple left semi-brace. Then the additive semigroup $(B, +)$ of B is a rectangular group.*

Proof. The thesis follows by [29, Corollary 3.5], which states that any completely simple semigroup with a middle unit is a rectangular group. □

A special case in which the additive semigroup is completely simple is when $0 + B$ is a subgroup of (B, \circ) (see [32, Theorem 2.8]). For instance, this is the case when B is finite.

The set of idempotents of a semigroup S will be denoted by $E(S)$. As a consequence of Theorem 2.3, we have that the additive semigroup $(B, +)$ can be written as

$$B = I + G + \Lambda,$$

that is, the direct sum of the left zero semigroup $I := E(B + 0)$, the group $G := 0 + B + 0$, and the right zero semigroup $\Lambda := E(0 + B)$. Moreover, the set of idempotents is $E(B) = I + \Lambda$ and it is a rectangular band.

For the sake of completeness, let us introduce a further property of middle units of left semi-braces that holds without restrictions on the additive semigroup. At first, we recall that the additive semigroup of a left semi-brace B does not contain a zero element if B has at least two elements (see [32, Lemma 2.3]).

In the following, we prove that middle units of the additive structure of an arbitrary left semi-brace are idempotents.

Proposition 2.4. *Let B be a left semi-brace. Then every middle unit $e \in B$ is an idempotent of the semi-group $(B, +)$.*

Proof. Since 0 is idempotent, we have that

$$e = e \circ 0 = e \circ (0 + 0) = e \circ 0 + e \circ (e^- + 0) = e + e \circ (e^- + 0).$$

Since e is a middle unit, it follows that

$$e + e = e + e + e \circ (e^- + 0) = e + e \circ (e^- + 0) = e,$$

which is our assertion. \square

Following Ault's paper [1, Theorem 1.8], by Proposition 2.4, we have that the additive semigroup of any left semi-brace contains a subsemigroup M_B , called the *semigroup of middle units of B* , that is explicitly given by

$$M_B = \{x \mid x \in B, x \text{ has inverse } x' \text{ with } x + x', x' + x \text{ middle units}\},$$

where the inverse x' of x means that $x' = x' + x + x'$ and $x = x + x' + x$.

Then M_B is a subsemigroup of $(B, +)$ that is a rectangular group. This is an interesting substructure of a left semi-brace, which is beyond the purpose of this paper and shall be studied elsewhere.

Now, having as reference [7, Example 2], we provide the following class of examples of completely simple left semi-braces that allow one to obtain solutions.

Example 2.5. Let (B, \circ) be a group with identity 0, and let f, g be idempotent endomorphisms of (B, \circ) such that $fg = gf$. Let us consider the following operation:

$$a + b := b \circ fg(b^-) \circ f(a)$$

for all $a, b \in B$. It is easy to check that $(B, +, \circ)$ is a completely simple left semi-brace. Now, observe that the map ρ is an anti-homomorphism from the group (B, \circ) into the monoid B^B , where B^B denotes the monoid of the functions from B into itself. Indeed, ρ_b is given by

$$\rho_b(a) = (a^- + b)^- \circ b = (b \circ fg(b^-) \circ f(a^-))^- \circ b = f(a) \circ fg(b).$$

Moreover,

$$\rho_b \rho_a(c) = \rho_b(f(c) \circ fg(a)) = f^2(c) \circ f^2 g(a) \circ fg(b) = f(c) \circ fg(a \circ b) = \rho_{a \circ b}(c)$$

for all $a, b, c \in B$. Thus, by [32, Proposition 2.14], the semigroup $(B, +)$ is completely simple.

In addition, since ρ is an anti-homomorphism of the group (B, \circ) , we obtain that the map $r : B \times B \rightarrow B \times B$ defined by $r(a, b) = (\lambda_a(b), \rho_b(a))$ in [32, Theorem 5.1] is a solution. Note that $\lambda_a(b) = a \circ b \circ fg(b^-) \circ f(a^-)$. Therefore, r is explicitly given by

$$r(a, b) = (a \circ b \circ fg(b^-) \circ f(a^-), f(a \circ g(b)))$$

for all $a, b \in B$.

Let us examine special cases of the previous class of examples. Firstly, observe that if $f \neq \text{id}$ and g is not the constant map of value 0, then the semigroup $(B, +)$ is neither left nor right cancellative. Moreover, note the following three cases:

Case 1. If g is the constant map of value 0, then

$$a + b = b \circ f(0) \circ f(a) = b \circ f(a)$$

for all $a, b \in B$, i.e., B coincides with the left cancellative left semi-brace provided in [7, Example 2]. Moreover, the solution associated to B is given by

$$r(a, b) = (a \circ b \circ f(a^-), f(a)).$$

Case 2. If $f = \text{id}$, then

$$a + b = b \circ g(b^-) \circ a$$

for all $a, b \in B$. In this case, the semigroup $(B, +)$ is right cancellative. Indeed, if $a + b = c + b$, it follows that $b \circ g(b^-) \circ a = b \circ g(b^-) \circ c$, and so $a = c$. Moreover, it is easy to check that B is both a right and left semi-brace. In addition, note that the solution associated to B is given by

$$r(a, b) = (a \circ b \circ g(b^-) \circ a^-, a \circ g(b)).$$

Case 3. If $f = g$, then

$$a + b = b \circ f^2(b^-) \circ f(a) = b \circ f(b^-) \circ f(a)$$

for all $a, b \in B$. Note that if $a \in B$, it holds

$$a + a = a \circ f(a^-) \circ f(a) = a,$$

i.e., every element is idempotent with respect to the sum. In this case, the semigroup $(B, +)$ is a rectangular band where $\ker f = 0 + B$ and $\text{im } f = B + 0$. Moreover, the solution r associated to B , given by

$$r(a, b) = (a \circ b \circ f(b^- \circ a^-), f(a \circ b)),$$

is an idempotent solution, consistently with [32, Theorem 5.1] in the case in which $G = \{0\}$.

The following is a class of examples of completely simple left semi-braces that, under suitable assumptions, give rise to solutions.

Example 2.6. Let G, H be two groups, let $B := G \times H$ and consider the group (B, \circ) where

$$(a, u) \circ (b, v) = (a^u b, u^b v)$$

for all $(a, u), (b, v) \in G \times H$, i.e., the classical Zappa–Szép product of G and H (see [36]) that has identity $(1, 1)$. Let φ be a map from G into H such that $\varphi(1) = 1$ and define the following operation on B :

$$(a, u) + (b, v) = (a, u\varphi(b)v)$$

for all $(a, u), (b, v) \in G \times H$. It is easy to check that the structure $(B, +, \circ)$ is a left semi-brace. Let us note that $(B, +)$ is a left group. Moreover, (a, u) in $G \times H$ is idempotent with respect to the sum if and only if $\varphi(a) = u^{-1}$. In addition, if $(a, u), (b, v) \in E(B)$, we have that

$$(a, u) + (b, v) = (a, u\varphi(b)v) = (a, u).$$

Hence $E(B)$ is a sub-semigroup of $(B, +)$ and it is also a left zero semigroup. Note also that

$$(a, u) + (1, 1) = (a, u\varphi(1)1) = (a, u),$$

i.e., $(1, 1)$ is a right identity with respect to the sum. Furthermore, we have that

$$\rho_{(b,v)}(a, u) = ((\varphi(b)v)^{-1}(a^u b), (((\varphi(b)v)^{-1})^a u)^b v)$$

for all $(a, u), (b, v), (c, w) \in B$. One can check that ρ is an anti-homomorphism if and only if it holds

$$\varphi(b)v\varphi(c) = \varphi(b^v c)v^c \quad (2.1)$$

for all $a, b \in G$ and $u \in H$. Moreover, by the characterization [10, Theorem 3], one can verify that the map r in [32, Theorem 5.1] associated to the left semi-brace B is a solution if and only if

$$\varphi(a)u\varphi(b) = \varphi(b)v\varphi((\varphi(b)v)^{-1}(a^u b))(((\varphi(b)v)^{-1})^a u)^b \quad (2.2)$$

holds for all $a, b \in G$ and $u, v \in H$. On the other hand, note that, if $a, b \in G$ and $u \in H$, considering $v = \varphi(b)^{-1}$ in (2.2), we obtain

$$\varphi(a)u\varphi(b) = v^{-1}v\varphi((v^{-1})^{-1}(a^u b))(((v^{-1})^{-1})^a u)^b = \varphi(a^u b)u^b.$$

Hence (2.1) is satisfied.

Now, let G be the cyclic group C_2 of 2 elements, let H be the cyclic group C_3 of 3 elements, and let φ be the constant map of value 1 from G into H . Hence, if (B, \circ) is the cyclic group $C_2 \times C_3$, then condition (2.1) trivially holds, and hence r is a solution. Instead, if (B, \circ) is the symmetric group $C_2 \times C_3$, then (2.1) is not satisfied; equivalently, (2.2) does not hold, and hence r is not a solution.

3 Definitions and examples

Braces, skew braces, and semi-braces were introduced to study set-theoretic solutions of the Yang–Baxter equation. The following definition generalizes these structure to the case in which the multiplicative structure is no more a group.

At first, we recall that a semigroup (S, \circ) is *completely regular* if for any element a of S there exists a (unique) element a^- of S such that

$$a = a \circ a^- \circ a, \quad a^- = a^- \circ a \circ a^-, \quad a \circ a^- = a^- \circ a. \quad (3.1)$$

Conditions (3.1) imply that $a^0 := a \circ a^- = a^- \circ a$ is an idempotent element of (S, \circ) .

Definition 3.1. Let S be a set with two operations $+$ and \circ such that $(S, +)$ is a semigroup (not necessarily commutative) and (S, \circ) is a completely regular semigroup. Then we say that $(S, +, \circ)$ is a *generalized left semi-brace* if

$$a \circ (b + c) = a \circ b + a \circ (a^- + c) \quad (3.2)$$

for all $a, b, c \in S$. We call $(S, +)$ and (S, \circ) the *additive semigroup* and the *multiplicative semigroup* of S , respectively.

A *generalized right semi-brace* is defined similarly, replacing condition (3.2) by

$$(a + b) \circ c = (a + c^-) \circ c + b \circ c$$

for all $a, b, c \in S$.

A *generalized two-sided semi-brace* is a generalized left semi-brace that is also a generalized right semi-brace with respect to the same pair of operations.

Let us note that if S is a generalized left semi-brace and $a \in S$, then the map

$$\lambda_a : S \rightarrow S, \quad b \mapsto a \circ (a^- + b),$$

is an endomorphism of the semigroup $(S, +)$ and $\lambda_{a \circ b}(x) = (a \circ b)^0 + \lambda_a \lambda_b(x)$ for all $a, b, x \in S$. Indeed, if $a, b, x, y \in S$, we have that

$$\lambda_a(x + y) = a \circ (a^- + x + y) = a \circ (a^- + x) + a \circ (a^- + y) = \lambda_a(x) + \lambda_a(y)$$

and

$$\begin{aligned} \lambda_{a \circ b}(x) &= (a \circ b) \circ ((a \circ b)^- + x) \\ &= a \circ (b \circ (a \circ b)^- + b \circ (b^- + x)) \\ &= a \circ b \circ (a \circ b)^- + a \circ (a^- + \lambda_b(x)) \\ &= (a \circ b)^0 + \lambda_a \lambda_b(x). \end{aligned}$$

Of course, left semi-braces [7, 32] are examples of generalized left semi-braces. Moreover, a generalized left semi-brace can be obtained from every completely regular semigroup.

Example 3.2. If (S, \circ) is an arbitrary completely regular semigroup and $(S, +)$ is a right zero semigroup (or a left zero semigroup), then $(S, +, \circ)$ is a generalized two-sided semi-brace.

Unlike left semi-braces, a generalized left semi-brace S can have a zero element even if S has more than one element. Examples of such generalized left semi-braces can be easily obtained by any Clifford semigroup.

Example 3.3. If (S, \circ) is a Clifford semigroup, which is a completely regular semigroup where all idempotent elements are central, then $(S, +, \circ)$, where $a + b = a \circ b$ for all $a, b \in S$, is a generalized two-sided semi-brace.

More generally, the previous generalized left semi-braces can be obtained through the following construction.

Proposition 3.4. *Let Y be a (lower) semilattice, let $\{S_\alpha \mid \alpha \in Y\}$ be a family of disjoint generalized left semi-braces. For each pair α, β of elements of Y such that $\alpha \geq \beta$, let $\phi_{\alpha,\beta} : S_\alpha \rightarrow S_\beta$ be a homomorphism of generalized left semi-braces such that the following conditions hold:*

- (i) $\phi_{\alpha,\alpha}$ is the identical automorphism of S_α for every $\alpha \in Y$.
- (ii) $\phi_{\beta,\gamma}\phi_{\alpha,\beta} = \phi_{\alpha,\gamma}$ for all $\alpha, \beta, \gamma \in Y$ such that $\alpha \geq \beta \geq \gamma$.

Then $S = \bigcup\{S_\alpha \mid \alpha \in Y\}$ endowed by the addition and the multiplication defined by

$$\begin{aligned} a + b &= \phi_{\alpha,\alpha\beta}(a) + \phi_{\beta,\alpha\beta}(b), \\ a \circ b &= \phi_{\alpha,\alpha\beta}(a) \circ \phi_{\beta,\alpha\beta}(b) \end{aligned}$$

for any $a \in S_\alpha$ and $b \in S_\beta$, is a generalized left semi-brace. Such a generalized left semi-brace is said to be the strong semilattice Y of the generalized left semi-brace S_α and is denoted by $S = [Y; S_\alpha, \phi_{\alpha,\beta}]$.

Proof. First note that $(S, +)$ is a semigroup and (S, \circ) is a completely regular semigroup. Now, let $a \in S_\alpha$, $b \in S_\beta$, and $c \in S_\gamma$. Set $\delta := \alpha\beta$, $\varepsilon := \beta\gamma$, $\zeta := \alpha\gamma$, and $\eta := \alpha\beta\gamma$. It follows that

$$\begin{aligned} a \circ (b + c) &= a \circ (\phi_{\beta,\varepsilon}(b) + \phi_{\gamma,\varepsilon}(c)) \\ &= \phi_{\alpha,\eta}(a) \circ \phi_{\varepsilon,\eta}(\phi_{\beta,\varepsilon}(b) + \phi_{\gamma,\varepsilon}(c)) && \text{(since } \alpha\varepsilon = \eta) \\ &= \phi_{\alpha,\eta}(a) \circ (\phi_{\varepsilon,\eta}\phi_{\beta,\varepsilon}(b) + \phi_{\varepsilon,\eta}\phi_{\gamma,\varepsilon}(c)) \\ &= \phi_{\alpha,\eta}(a) \circ (\phi_{\beta,\eta}(b) + \phi_{\gamma,\eta}(c)) && \text{(by (ii))} \\ &= \phi_{\alpha,\eta}(a) \circ \phi_{\beta,\eta}(b) + \phi_{\alpha,\eta}(a) \circ ((\phi_{\alpha,\eta}(a))^- + \phi_{\gamma,\eta}(c)), \end{aligned}$$

where the last equality holds since S_η is a generalized left semi-brace. Moreover,

$$\begin{aligned} a \circ b + a \circ (a^- + c) &= \phi_{\alpha,\delta}(a) \circ \phi_{\beta,\delta}(b) + a \circ ((\phi_{\alpha,\zeta}(a))^- + \phi_{\gamma,\zeta}(c)) \\ &= \phi_{\alpha,\delta}(a) \circ \phi_{\beta,\delta}(b) + \phi_{\alpha,\zeta}(a) \circ ((\phi_{\alpha,\zeta}(a))^- + \phi_{\gamma,\zeta}(c)) \\ &= \phi_{\delta,\eta}(\phi_{\alpha,\delta}(a) \circ \phi_{\beta,\delta}(b)) + \phi_{\zeta,\eta}(\phi_{\alpha,\zeta}(a) \circ ((\phi_{\alpha,\zeta}(a))^- + \phi_{\gamma,\zeta}(c))) && \text{(since } \delta\zeta = \eta) \\ &= \phi_{\alpha,\eta}(a) \circ \phi_{\beta,\eta}(b) + \phi_{\alpha,\eta}(a) \circ ((\phi_{\alpha,\eta}(a))^- + \phi_{\gamma,\eta}(c)) && \text{(by (ii)).} \end{aligned}$$

Therefore, S is a generalized left semi-brace. □

Remark 3.5. If $S = [Y; S_\alpha, \phi_{\alpha,\beta}]$ is a strong semilattice Y of left semi-braces S_α , then (S, \circ) is a strong semilattice of groups, and hence, by [30, Theorem 4.2.1], (S, \circ) is a Clifford semigroup.

4 Solutions related to generalized left semi-braces

This section is devoted to provide a sufficient condition to obtain solutions through a generalized left semi-brace. To this end, we recall that if S is a left cancellative left semi-brace, then the map $r : S \times S \rightarrow S \times S$ given by

$$r(a, b) := (a \circ (a^- + b), (a^- + b)^- \circ b) \tag{4.1}$$

for all $a, b \in S$ is a solution. Moreover, [32, Theorem 5.1] gives a sufficient condition to obtain that the map in (4.1) is still a solution for a left semi-brace, not necessarily left cancellative. In addition, in [10, Theorem 3], we state a necessary and sufficient condition to ensure that r is a solution.

Specifically, if $(S, +, \circ)$ is a left semi-brace, then the map $r : S \times S \rightarrow S \times S$, defined by

$$r(a, b) := (a \circ (a^- + b), (a^- + b)^- \circ b) \quad \text{for all } a, b \in S,$$

is a solution if and only if

$$a + \lambda_b(c) \circ (0 + \rho_c(b)) = a + b \circ (0 + c) \tag{4.2}$$

holds for all $a, b, c \in S$.

Let us remark that if S is a generalized left semi-brace with $(S, +)$ being a right zero semigroup, then the map r as in (4.1) is a solution if and only if $(a \circ b)^0 = (a^0 \circ b)^0$ holds for all $a, b \in S$. Observe that semi-groups (S, \circ) satisfying such a condition lie in the wide class of right cryptogroups; see [42]. In this way, we get new idempotent solutions that are of the form $r(a, b) = (a^0, a \circ b)$, different from those obtained in [19, 37, 39, 48].

Moreover, note that if $(S, +, \circ)$ is the generalized left semi-brace of Example 3.3, we obtain that

$$r(a, b) = (a^0 \circ b, b^- \circ a \circ b)$$

is a solution. In particular, if (S, \circ) is commutative, clearly $r(a, b) = (a^0 \circ b, b^0 \circ a)$ and it is easy to verify that r is a cubic solution, i.e., $r^3 = r$.

Our aim is to show that if $S = [Y; S_\alpha, \phi_{\alpha,\beta}]$ is a strong semilattice of generalized left semi-braces such that every S_α satisfies condition (4.2), then the map in (4.1) is a solution. This result is a consequence of a more general construction technique on solutions we introduce in the following theorem.

Theorem 4.1. *Let Y be a (lower) semilattice, let $\{(X_\alpha, r_\alpha) \mid \alpha \in Y\}$ be a family of disjoint solutions indexed by Y such that for each pair $\alpha, \beta \in Y$ with $\alpha \geq \beta$ there is a map $\phi_{\alpha,\beta} : X_\alpha \rightarrow X_\beta$. Let X be the union*

$$X = \bigcup \{X_\alpha \mid \alpha \in Y\}$$

and let $r : X \times X \rightarrow X \times X$ be the map defined by

$$r(x, y) := r_{\alpha\beta}(\phi_{\alpha,\alpha\beta}(x), \phi_{\beta,\alpha\beta}(y))$$

for all $x \in X_\alpha$ and $y \in X_\beta$. Then (X, r) is a solution if the following conditions are satisfied:

- (i) $\phi_{\alpha,\alpha}$ is the identity map of X_α for every $\alpha \in Y$.
- (ii) $\phi_{\beta,\gamma}\phi_{\alpha,\beta} = \phi_{\alpha,\gamma}$ for all $\alpha, \beta, \gamma \in Y$ such that $\alpha \geq \beta \geq \gamma$.
- (iii) $(\phi_{\alpha,\beta} \times \phi_{\alpha,\beta})r_\alpha = r_\beta(\phi_{\alpha,\beta} \times \phi_{\alpha,\beta})$ for all $\alpha, \beta \in Y$ such that $\alpha \geq \beta$.

We call the pair (X, r) a strong semilattice of solutions (X_α, r_α) indexed by Y .

The proof of Theorem 4.1 is technical, and for the sake of clarity, we present it in the next section. Now, as a consequence of this theorem, we obtain the following result.

Theorem 4.2. *Let $S = [Y; S_\alpha, \phi_{\alpha,\beta}]$ be a strong semilattice of generalized left semi-braces. Then, if S_α satisfies (4.2) for every $\alpha \in Y$, then the map $r_S : S \times S \rightarrow S \times S$ defined by*

$$r(a, b) := (a \circ (a^- + b), (a^- + b)^- \circ b)$$

for all $a, b \in S$ is a solution.

Proof. For any $\alpha \in Y$, let $r_\alpha : S_\alpha \times S_\alpha \rightarrow S_\alpha \times S_\alpha$ be the solution associated to the left semi-brace S_α , i.e., the map defined by $r_\alpha(x, y) = (x \circ (x^- + y), (x^- + y)^- \circ y)$. Since S is a strong semilattice of left semi-braces, by Proposition 3.4, $\phi_{\alpha,\alpha}$ is the identical automorphism of S_α and $\phi_{\beta,\gamma}\phi_{\alpha,\beta} = \phi_{\alpha,\gamma}$ for all $\alpha, \beta, \gamma \in Y$ such that $\alpha \geq \beta \geq \gamma$. Hence, conditions (i) and (ii) in Theorem 4.1 are satisfied. Moreover, let $a, b \in Y$ such that $\alpha \geq \beta$. Since, $\phi_{\alpha,\beta}$ is a homomorphism of left semi-braces, for all $x, y \in S_\alpha$ it follows that

$$\begin{aligned} (\phi_{\alpha,\beta} \times \phi_{\alpha,\beta})r_\alpha(x, y) &= (\phi_{\alpha,\beta}(x \circ (x^- + y)), \phi_{\alpha,\beta}((x^- + y)^- \circ y)) \\ &= (\phi_{\alpha,\beta}(x) \circ ((\phi_{\alpha,\beta}(x))^- + \phi_{\alpha,\beta}(y)), ((\phi_{\alpha,\beta}(x))^- + \phi_{\alpha,\beta}(y))^- \circ \phi_{\alpha,\beta}(y)) \\ &= r_\beta(\phi_{\alpha,\beta}(x), \phi_{\alpha,\beta}(y)) \\ &= r_\beta(\phi_{\alpha,\beta} \times \phi_{\alpha,\beta})(x, y). \end{aligned}$$

Hence Theorem 4.1 (iii) holds. Therefore, according to Theorem 4.1, we shall consider the strong semilattice Y of solutions r_α , i.e., the map r defined by

$$r(x, y) = r_{\alpha\beta}(\phi_{\alpha,\alpha\beta}(x), \phi_{\beta,\alpha\beta}(y))$$

for all $x \in S_\alpha, y \in S_\beta$. Finally, note that, by Proposition 3.4,

$$\begin{aligned} r(x, y) &= (\phi_{\alpha, \alpha\beta}(x) \circ ((\phi_{\alpha, \alpha\beta}(x))^- + \phi_{\beta, \alpha\beta}(y)), ((\phi_{\alpha, \alpha\beta}(x))^- + \phi_{\beta, \alpha\beta}(y))^- \circ \phi_{\beta, \alpha\beta}(y)) \\ &= (x \circ (x^- + y), (x^- + y)^- \circ y) \end{aligned}$$

for all $x \in S_\alpha, y \in S_\beta$. □

5 Strong semilattices of set-theoretical solutions

This section aims to provide a proof of Theorem 4.1 and to give some examples of strong semilattices of solutions. Furthermore, we analyze strong semilattices of solutions with finite order.

Proof of Theorem 4.1. At first, note that if $\lambda_x^{[\omega]}$ and $\rho_y^{[\omega]}$ are the maps from X_ω into itself that define every solution r_ω , i.e., r_ω is written as

$$r_\omega(x, y) = (\lambda_x^{[\omega]}(y), \rho_y^{[\omega]}(x))$$

for all $x, y \in X_\omega$, then condition (iii) is equivalent to the following equalities:

$$\phi_{\omega, t} \lambda_x^{[\omega]}(y) = \lambda_{\phi_{\omega, t}(x)}^{[t]} \phi_{\omega, t}(y), \quad (5.1)$$

$$\phi_{\omega, t} \rho_y^{[\omega]}(x) = \rho_{\phi_{\omega, t}(y)}^{[t]} \phi_{\omega, t}(x) \quad (5.2)$$

for all $\omega, t \in Y$ such that $\omega \geq t$ and $x, y \in X_\omega$. In addition, let us observe that if $x \in X_\omega$ and $y \in Y_t$, then the two components of the map r , i.e.,

$$\lambda_x(y) = \lambda_{\phi_{\omega, \omega t}(x)}^{[\omega t]} \phi_{t, \omega t}(y), \quad \rho_y(x) = \rho_{\phi_{t, \omega t}(y)}^{[\omega t]} \phi_{\omega, \omega t}(x),$$

lie in $X_{\omega t}$, consistently with the second part of the subscript of the maps ϕ . To avoid overloading the notation, hereinafter we will write the previous elements as

$$\lambda_x(y) = \lambda_{\phi_{\omega, \omega t}(x)} \phi_{t, \omega t}(y), \quad \rho_y(x) = \rho_{\phi_{t, \omega t}(y)} \phi_{\omega, \omega t}(x).$$

Now, we verify that r is a solution proving that the relations

$$\begin{aligned} L_1 &:= \lambda_x \lambda_y(z) = \lambda_{\lambda_x(y)} \lambda_{\rho_y(x)}(z) =: L_2, \\ C_1 &:= \lambda_{\rho_{\lambda_y(z)}(x)} \rho_z(y) = \rho_{\lambda_{\rho_y(x)}(z)} \lambda_x(y) =: C_2, \\ R_2 &:= \rho_{\rho_y(z)} \rho_{\lambda_z(y)}(x) = \rho_z \rho_y(x) =: R_1 \end{aligned}$$

are satisfied for all $x, y, z \in X$. For this purpose, let x, y, z be elements of X_ω, X_t, X_κ , respectively, and assume $v := \omega t \kappa$ and

$$\mathcal{X} := \phi_{\omega, v}(x), \quad \mathcal{Y} := \phi_{t, v}(y), \quad \mathcal{Z} := \phi_{\kappa, v}(z) \quad (\text{in } X_v).$$

Setting

$$U := \rho_{\phi_{t, \omega t}(y)} \phi_{\omega, \omega t}(x), \quad V := \lambda_{\phi_{\omega, \omega t}(x)} \phi_{t, \omega t}(y) \quad (\text{in } X_{\omega t}),$$

we have that

$$\begin{aligned} L_2 &= \lambda_{\lambda_x(y)} \lambda_{\rho_y(x)}(z) \\ &= \lambda_V \lambda_U(z) \\ &= \lambda_V \lambda_{\phi_{\omega t, v}(U)} \phi_{\kappa, v}(z) \quad (v = \omega t \kappa) \\ &= \lambda_{\phi_{\omega t, \omega t v}(V)} \phi_{v, \omega t v} \lambda_{\phi_{\omega t, v}(U)}(\mathcal{Z}) \\ &= \lambda_{\phi_{\omega t, v}(V)} \phi_{v, v} \lambda_{\phi_{\omega t, v}(U)}(\mathcal{Z}) \quad (\omega t v = v) \\ &= \lambda_{\phi_{\omega t, v}(V)} \lambda_{\phi_{\omega t, v}(U)}(\mathcal{Z}) \quad (\phi_{v, v} = \text{id}_{X_v}). \end{aligned}$$

Since

$$\begin{aligned}\phi_{\omega l, v}(V) &= \lambda_{\phi_{\omega l, v} \phi_{\omega, \omega l}(x)} \phi_{\omega l, v} \phi_{l, \omega l}(y) \quad (\text{by (5.1)}) \\ &= \lambda_{\phi_{\omega, v}(x)} \phi_{l, v}(y) \quad (\phi_{\omega l, v} \phi_{\omega, \omega l} = \phi_{\omega, v}, \phi_{\omega l, v} \phi_{l, \omega l} = \phi_{l, v}) \\ &= \lambda_{\mathcal{X}}(\mathcal{Y})\end{aligned}$$

and

$$\begin{aligned}\phi_{\omega l, v}(U) &= \rho_{\phi_{\omega l, v} \phi_{l, \omega l}(y)} \phi_{\omega l, v} \phi_{\omega, \omega l}(x) \quad (\text{by (5.2)}) \\ &= \rho_{\phi_{l, v}(y)} \phi_{\omega, v}(x) \quad (\phi_{\omega l, v} \phi_{l, \omega l} = \phi_{l, v}, \phi_{\omega l, v} \phi_{\omega, \omega l} = \phi_{\omega, v}) \\ &= \rho_{\mathcal{Y}}(\mathcal{X}),\end{aligned}$$

it follows that

$$\begin{aligned}L_2 &= \lambda_{\lambda_{\mathcal{X}}(\mathcal{Y})} \lambda_{\rho_{\mathcal{Y}}(\mathcal{X})}(\mathcal{Z}) \quad (\text{in } X_v) \\ &= \lambda_{\mathcal{X}} \lambda_{\mathcal{Y}}(\mathcal{Z}) \quad (r_v \text{ is a solution}).\end{aligned}$$

Moreover, it holds

$$\begin{aligned}L_1 &= \lambda_{\mathcal{X}} \lambda_{\mathcal{Y}}(\mathcal{Z}) = \lambda_{\mathcal{X}} \lambda_{\phi_{l, ik}(y)} \phi_{\kappa, ik}(z) \\ &= \lambda_{\phi_{\omega, v}(x)} \phi_{ik, v} \lambda_{\phi_{l, ik}(y)} \phi_{\kappa, ik}(z) \quad (v = \omega ik) \\ &= \lambda_{\mathcal{X}} \lambda_{\phi_{ik, v} \phi_{l, ik}(y)} \phi_{ik, v} \phi_{\kappa, ik}(z) \quad (\text{by (5.1)}) \\ &= \lambda_{\mathcal{X}} \lambda_{\phi_{l, v}(y)} \phi_{\kappa, v}(z) \quad (\phi_{ik, v} \phi_{l, ik} = \phi_{l, v}, \phi_{ik, v} \phi_{\kappa, ik} = \phi_{\kappa, v}) \\ &= \lambda_{\mathcal{X}} \lambda_{\mathcal{Y}}(\mathcal{Z}).\end{aligned}$$

Hence we obtain that $L_1 = L_2$. Now, setting

$$W := \rho_{\phi_{\kappa, ik}(z)} \phi_{l, ik}(y), \quad Z := \lambda_{\phi_{l, ik}(y)} \phi_{\kappa, ik}(z) \quad (\text{in } X_{ik}),$$

observe that

$$\begin{aligned}C_1 &= \lambda_{\rho_{\lambda_{\mathcal{Y}}(z)}(x)} \rho_{\mathcal{Z}}(y) \\ &= \lambda_{\rho_{\lambda_{\phi_{l, ik}(y)} \phi_{\kappa, ik}(z)}(x)} \rho_{\phi_{\kappa, ik}(z)} \phi_{l, ik}(y) \\ &= \lambda_{\rho_{\mathcal{Z}}(x)}(W) \\ &= \lambda_{\rho_{\phi_{ik, v}(z)} \phi_{\omega, v}(x)}(W) \quad (v = \omega ik) \\ &= \lambda_{\phi_{v, vik} \rho_{\phi_{ik, v}(z)}(\mathcal{X})} \phi_{ik, vik}(W) \\ &= \lambda_{\phi_{v, v} \rho_{\phi_{ik, v}(z)}(\mathcal{X})} \phi_{ik, v}(W) \quad (vik = v) \\ &= \lambda_{\rho_{\phi_{ik, v}(z)}(\mathcal{X})} \phi_{ik, v}(W) \quad (\phi_{v, v} = \text{id}_{X_v}).\end{aligned}$$

Since

$$\begin{aligned}\phi_{ik, v}(Z) &= \lambda_{\phi_{ik, v} \phi_{l, ik}(y)} \phi_{ik, v} \phi_{\kappa, ik}(z) \quad (\text{by (5.1)}) \\ &= \lambda_{\phi_{l, v}(y)} \phi_{\kappa, v}(z) \quad (\phi_{ik, v} \phi_{l, ik} = \phi_{l, v}, \phi_{ik, v} \phi_{\kappa, ik} = \phi_{\kappa, v}) \\ &= \lambda_{\mathcal{Y}}(\mathcal{Z})\end{aligned}$$

and

$$\begin{aligned}\phi_{ik, v}(W) &= \rho_{\phi_{ik, v} \phi_{\kappa, ik}(z)} \phi_{ik, v} \phi_{l, ik}(y) \quad (\text{by (5.2)}) \\ &= \rho_{\phi_{\kappa, v}(z)} \phi_{l, v}(y) \quad (\phi_{ik, v} \phi_{\kappa, ik} = \phi_{\kappa, v}, \phi_{ik, v} \phi_{l, ik} = \phi_{l, v}) \\ &= \rho_{\mathcal{Z}}(\mathcal{Y}),\end{aligned}$$

it follows that

$$C_1 = \lambda_{\rho_{\lambda_{\mathcal{Y}}(Z)}(\mathcal{X})} \rho_Z(\mathcal{Y}) \quad (\text{in } X_V).$$

Furthermore, since U and V lie in $X_{\omega I}$, we have

$$\begin{aligned} C_2 &= \rho_{\lambda_{\rho_{\mathcal{Y}}(X)}(Z)} \lambda_X(\mathcal{Y}) \\ &= \rho_{\lambda_{\rho_{\phi_{I,\omega I}(Y)} \phi_{\omega,\omega I}(X)}(Z)} \lambda_{\phi_{\omega,\omega I}(X)} \phi_{I,\omega I}(Y) \\ &= \rho_{\lambda_U(Z)}(V) \\ &= \rho_{\lambda_{\phi_{\omega I,V}(U)} \phi_{\kappa,V}(Z)}(V) && (v = \omega I \kappa) \\ &= \rho_{\phi_{V,\omega IV} \lambda_{\phi_{\omega I,V}(U)}(Z)} \phi_{\omega I,\omega IV}(V) \\ &= \rho_{\phi_{V,V} \lambda_{\phi_{\omega I,V}(U)}(Z)} \phi_{\omega I,V}(V) && (\omega IV = v) \\ &= \rho_{\lambda_{\phi_{\omega I,V}(U)}(Z)} \phi_{\omega I,V}(V) && (\phi_{V,V} = \text{id}_{X_V}). \end{aligned}$$

As seen before, $\phi_{\omega I,V}(U) = \rho_{\mathcal{Y}}(\mathcal{X})$ and $\phi_{\omega I,V}(V) = \lambda_{\mathcal{X}}(\mathcal{Y})$. Thus

$$C_2 = \rho_{\lambda_{\rho_{\mathcal{Y}}(\mathcal{X})}(Z)} \lambda_{\mathcal{X}}(\mathcal{Y}) \quad (\text{in } X_V).$$

Consequently, since r_V is a solution, we obtain that $C_1 = C_2$.

Finally, since W and Z lie in $X_{I\kappa}$, note that

$$\begin{aligned} R_2 &= \rho_{\rho_{\mathcal{Y}}(Z)} \rho_{\lambda_{\mathcal{Z}}(Y)}(X) \\ &= \rho_{\rho_{\phi_{\kappa,I\kappa}(Z)} \phi_{I,I\kappa}(Y)} \rho_{\lambda_{\phi_{I,I\kappa}(Y)} \phi_{\kappa,I\kappa}(Z)}(X) \\ &= \rho_W \rho_Z(X) \\ &= \rho_W \rho_{\phi_{I\kappa,V}(Z)} \phi_{\omega,V}(X) && (v = \omega I \kappa) \\ &= \rho_{\phi_{I\kappa,V\kappa}(W)} \phi_{V,V\kappa} \rho_{\phi_{I\kappa,V}(Z)}(\mathcal{X}) \\ &= \rho_{\phi_{I\kappa,V}(W)} \phi_{V,V} \rho_{\phi_{I\kappa,V}(Z)}(\mathcal{X}) && (v I \kappa = v) \\ &= \rho_{\phi_{I\kappa,V}(W)} \rho_{\phi_{I\kappa,V}(Z)}(\mathcal{X}) && (\phi_{V,V} = \text{id}_{X_V}). \end{aligned}$$

As seen before, $\phi_{I\kappa,V}(W) = \rho_Z(\mathcal{Y})$. In addition, we have

$$\begin{aligned} \phi_{I\kappa,V}(Z) &= \lambda_{\phi_{I\kappa,V} \phi_{I,I\kappa}(Y)} \phi_{I\kappa,V} \phi_{\kappa,I\kappa}(Z) \quad (\text{by (5.1)}) \\ &= \lambda_{\phi_{I,V}(Y)} \phi_{\kappa,V}(Z) && (\phi_{I\kappa,V} \phi_{I,I\kappa} = \phi_{I,V}, \phi_{I\kappa,V} \phi_{\kappa,I\kappa} = \phi_{\kappa,V}) \\ &= \lambda_{\mathcal{Y}}(\mathcal{Z}). \end{aligned}$$

It follows that

$$\begin{aligned} R_2 &= \rho_{\rho_Z(\mathcal{Y})} \rho_{\lambda_{\mathcal{Y}}(Z)}(\mathcal{X}) \quad (\text{in } X_V) \\ &= \rho_Z \rho_{\mathcal{Y}}(\mathcal{X}) && (r_V \text{ is a solution}). \end{aligned}$$

Moreover, it holds

$$\begin{aligned} R_1 &= \rho_Z \rho_{\mathcal{Y}}(X) = \rho_Z \rho_{\phi_{I,\omega I}(Y)} \phi_{\omega,\omega I}(X) \\ &= \rho_{\phi_{\kappa,V}(Z)} \phi_{\omega I,V} \rho_{\phi_{I,\omega I}(Y)} \phi_{\omega,\omega I}(X) \\ &= \rho_Z \rho_{\phi_{\omega I,V} \phi_{I,\omega I}(Y)} \phi_{\omega I,V} \phi_{\omega,\omega I}(X) \quad (\text{by (5.2)}) \\ &= \rho_Z \rho_{\phi_{I,V}(Y)} \phi_{\omega,V}(X) && (\phi_{\omega I,V} \phi_{I,\omega I} = \phi_{I,V}, \phi_{\omega I,V} \phi_{\omega,\omega I} = \phi_{\omega,V}) \\ &= \rho_Z \rho_{\mathcal{Y}}(\mathcal{X}), \end{aligned}$$

and hence $R_1 = R_2$. Therefore, the map r is a solution. \square

One can use strong semilattices of solutions (X, r) with r_α 's of finite order to produce examples of new solutions with finite order.

Examples 5.1. (i) Let X be a semilattice of sets indexed by Y such that conditions (i) and (ii) of Theorem 4.1 are satisfied and let r_α be the twist map on X_α for every $\alpha \in Y$. Then, if $\alpha \geq \beta$, we have that

$$\begin{aligned}\phi_{\alpha,\beta}\lambda_x(y) &= \phi_{\alpha,\beta}(y) = \lambda_{\phi_{\alpha,\beta}(x)}\phi_{\alpha,\beta}(y), \\ \phi_{\alpha,\beta}\rho_y(x) &= \phi_{\alpha,\beta}(x) = \rho_{\phi_{\alpha,\beta}(y)}\phi_{\alpha,\beta}(x)\end{aligned}$$

for all $x, y \in X_\alpha$, i.e., condition (iii) of Theorem 4.1 holds. Hence, the strong semilattice of solutions (X, r) is such that $r^3 = r$. Indeed, if $x \in X_\alpha$ and $y \in X_\beta$, assuming $v := \alpha\beta$, we have that $r(x, y) = r_v(\phi_{\alpha,v}(x), \phi_{\beta,v}(y))$. Hence $r^2(x, y) = (\phi_{\alpha,v}(x), \phi_{\beta,v}(y))$, and so

$$r^3(x, y) = r_v(\phi_{\alpha,v}(x), \phi_{\beta,v}(y)) = r(x, y).$$

Consequently, $r^3 = r$.

(ii) Let $X := X_\alpha \cup X_\beta$ be a semilattice of sets such that $\alpha > \beta$, let c be a fixed element of X_β , and let $\phi_{\alpha,\beta}(x) = c$ for every $x \in X_\alpha$. Let r_α be the twist map on X_α and let r_β be the idempotent solution on X_β defined by $r_\beta(x, y) := (x, c)$ for all $x, y \in X_\beta$. Then, if $x, y \in X_\alpha$, we have that

$$\begin{aligned}\phi_{\alpha,\beta}\lambda_x(y) &= c = \phi_{\alpha,\beta}(x) = \lambda_{\phi_{\alpha,\beta}(x)}\phi_{\alpha,\beta}(y), \\ \phi_{\alpha,\beta}\rho_y(x) &= c = \rho_{\phi_{\alpha,\beta}(y)}\phi_{\alpha,\beta}(x).\end{aligned}$$

Hence the assumptions of Theorem 4.1 are satisfied. Moreover, the strong semilattice of solutions (X, r) is such that $r^3 = r$. Indeed, if $x \in X_\alpha$ and $y \in X_\beta$, since $r(x, y) = r_\beta(\phi_{\alpha,\beta}(x), y) = r_\beta(c, y) = (c, c)$, it follows that

$$r^2(x, y) = r_\beta(c, c) = (c, c) = r(x, y).$$

Therefore, we obtain that $r^3 = r$.

(iii) Let $X := X_\alpha \cup X_\beta$ be a semilattice of sets such that $\alpha > \beta$, let c be a fixed element of X_β , and let $\phi_{\alpha,\beta}(x) = c$ for every $x \in X_\alpha$. Let f be an idempotent map from X_β into itself, $f \neq \text{id}_{X_\beta}$, and let r_α be the map from $X_\alpha \times X_\alpha$ into itself defined by $r_\alpha(x, y) := (f(x), x)$ for all $x, y \in X_\alpha$. Thus, r_α is a solution such that $r_\alpha^3 = r_\alpha^2$. Let r_β be the idempotent solution defined by $r_\beta(x, y) = (x, c)$ for all $x, y \in X_\beta$. Then, if $x, y \in X_\alpha$, we obtain that

$$\begin{aligned}\phi_{\alpha,\beta}\lambda_x(y) &= c = \phi_{\alpha,\beta}(x) = \lambda_{\phi_{\alpha,\beta}(x)}\phi_{\alpha,\beta}(y), \\ \phi_{\alpha,\beta}\rho_y(x) &= c = \rho_{\phi_{\alpha,\beta}(y)}\phi_{\alpha,\beta}(x).\end{aligned}$$

Thus the hypotheses of Theorem 4.1 are satisfied. Moreover, the strong semilattice of solutions (X, r) is such that $r^3 = r^2$. Indeed, if $x \in X_\alpha$ and $y \in X_\beta$, since $r(x, y) = r_\beta(\phi_{\alpha,\beta}(x), y) = r_\beta(c, y) = (c, c)$, it follows that

$$r^2(x, y) = r_\beta(c, c) = (c, c) = r(x, y),$$

and clearly $r^3(x, y) = r^2(x, y)$. Therefore, $r^3 = r^2$.

To investigate strong semilattices of solutions with finite order, we need the notions of the index and the period of a solution r that are

$$\begin{aligned}i(r) &:= \min\{j \mid j \in \mathbb{N}_0, \text{ there exists } l \in \mathbb{N} \text{ such that } r^j = r^l, j \neq l\}, \\ p(r) &:= \min\{k \mid k \in \mathbb{N}, r^{i(r)+k} = r^{i(r)}\},\end{aligned}$$

respectively. These definitions of the index and the order are slightly different from the classical ones (cf. [31, p. 10]), but they are functional to distinguish bijective solutions from non-bijective ones. For more details, we refer the reader to [10].

In the following theorem, we show that, given a semilattice Y of finite cardinality, the strong semilattice of solutions (X, r) indexed by Y is of finite order if and only if solutions r_α are. Furthermore, it allows for establishing the order of the strong semilattice of solutions (X, r) if the index and the period of solutions r_α are known. Conversely, the index and the period of a strong semilattice of solutions (X, r) give us upper bounds of the indexes and periods of solutions r_α .

Theorem 5.2. *Let (X, r) be a strong semilattice of solutions indexed by a finite semilattice Y . Then r_α is a solution with finite order on X_α for every $\alpha \in Y$ if and only if r is a solution with finite order. More precisely, the index of r is*

$$i(r) = \max\{1, i(r_\alpha) \mid \alpha \in Y\}$$

and the period is

$$p(r) = \text{lcm}\{p(r_\alpha) \mid \alpha \in Y\}.$$

Proof. At first, suppose that r_α is a solution with finite order for every $\alpha \in Y$. Let $n := \text{lcm}\{p(r_\alpha) \mid \alpha \in Y\}$ and $i := \max\{i(r_\alpha) \mid \alpha \in Y\}$. If $x \in X_\alpha$ and $y \in X_\beta$, setting $v := \alpha\beta$, we have that

$$r^{n+i}(x, y) = r_v^{n+i}(\phi_{\alpha,v}(x), \phi_{\beta,v}(y)) = r_v^i(\phi_{\alpha,v}(x), \phi_{\beta,v}(y)).$$

Consequently, if $i = 0$, i.e., r_α is bijective for every $\alpha \in Y$, we obtain that

$$r^{n+1}(x, y) = r_v(\phi_{\alpha,v}(x), \phi_{\beta,v}(y)) = r(x, y).$$

Therefore, $r^{n+1} = r$ and clearly the index of r is 1 by the assumption on i . Now, assume that $i \neq 0$ and that $i = i(r_\gamma)$ for a certain $\gamma \in Y$. If $r^n = r^h$, for a positive integer h , in particular, we have that $r_\gamma^n = r_\gamma^h$. Since $n = p(r_\gamma)q + i$ for a certain natural number q , it follows that

$$r_\gamma^{p(r_\gamma)+i} = r_\gamma^i = r_\gamma^{p(r_\gamma)q+i} = r_\gamma^n = r_\gamma^h.$$

Hence $i \leq h$, and so $i(r) = i$.

Now, we proceed to determine the period of r . If $r^m = r^{i(r)}$ for a natural number m , then $r_\alpha^m = r_\alpha^{i(r)}$ for every $\alpha \in Y$. Consequently, $p(r_\alpha)$ divides $m - i(r)$ for every $\alpha \in Y$. Thus $\text{lcm}\{p(r_\alpha) \mid \alpha \in Y\}$ divides $m - i(r)$, i.e., $n - i(r)$ divides $m - i(r)$. Therefore, $n - i(r) \leq m - i(r)$, and hence $p(r) = n - i(r)$. Conversely, suppose that the solution r is with finite order and set $i := i(r)$ and $p := p(r)$. If $\alpha \in Y$, since $\phi_{\alpha,\alpha} = \text{id}_{X_\alpha \times X_\alpha}$, we obtain that $r_\alpha^{p+i} = r_\alpha^i$. Therefore, r_α is a solution with finite order. Clearly, we have that $i(r_\alpha)$ is less than i and $p(r_\alpha)$ divides p . \square

Let us note that if (X, r) is a strong semilattice of non-bijective solutions r_α such that $i(r_\alpha) = i$ and $p(r_\alpha) = n$ for every $\alpha \in Y$, then r is still a solution of index i and period n , also in the case of an infinite semilattice Y . Indeed, one can prove this statement by similar computations used for the non-bijective case in the proof of Theorem 5.2.

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