## **Artificially Intelligent Foraging**

Submitted by Daniel Chalk, to the University of Exeter as a thesis for the degree of Doctor of Philosophy in Biosciences, December 2009.

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#### **Abstract**

Bumble bees (*bombus spp.*) are significant pollinators of many plants, and are particularly attracted to mass-flowering crops such as Oilseed Rape (*Brassica Napus*), which they crosspollinate. *B. napus* is both wind and insect-pollinated, and whilst it has been found that wind is its most significant pollen vector, the influence of bumble bee pollination could be non-trivial when bee densities are large. Therefore, the assessment of pollinator-mediated cross-pollination events could be important when considering containment strategies of genetically modified (GM) crops, such as GM varieties of *B. napus*, but requires a landscape-scale understanding of pollinator movements, which is currently unknown for bumble bees.

I developed an *in silico* model, entitled HARVEST, which simulates the foraging and consequential inter-patch movements of bumble bees. The model is based on principles from Reinforcement Learning and Individual Based Modelling, and uses a Linear Operator Learning Rule to guide agent learning. The model incoproates one or more agents, or bees, that learn by 'trial-and-error', with a gradual preference shown for patch choice actions that provide increased rewards.

To validate the model, I verified its ability to replicate certain iconic patterns of bee-mediated gene flow, and assessed its accuracy in predicting the flower visits and inter-patch movement frequencies of real bees in a small-scale system. The model successfully replicated the iconic patterns, but failed to accurately predict outputs from the real system. It did, however, qualitatively replicate the high levels of inter-patch traffic found in the real small-scale system, and its quantitative discrepancies could likely be explained by inaccurate parameterisations. I also found that HARVEST bees are extremely efficient foragers, which agrees with evidence of powerful learning capabilities and risk-aversion in real bumble bees.

When applying the model to the landscape-scale, HARVEST predicts that overall levels of beemediated gene flow are extremely low. Nonetheless, I identified an effective containment strategy in which a 'shield' comprised of sacrificed crops is placed between GM and conventional crop populations. This strategy could be useful for scenarios in which the tolerance for GM seed set is exceptionally low.

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### **List of Parameters**

Parameter	Identifier
ξ	Proportion of sink patch's seed with source patch paternity mediated by cross-pollination
Е	Fraction of pollinators arriving at sink from source
Ψ	Number of fruits fully fertilised in sink with source pollen by each pollinator in a sink visit
b	Total sink fruits fertilised by each pollinator in a sink visit
В	Number of bees in the grid
$B_{E}$	Estimated number of bees in the grid
L	Number of patches in landscape
Q	Initial quality of patches
Q(i)	Actual quality of patch i
q(i)	Estimated quality of patch i
β	Sensitivity to individual flower sample
s(i)	Value of the reward from latest sample in patch i
v(i, j)	Action-value for visiting patch j when currently in patch i
С	Bee's nectar carrying capacity
С	Bee's remaining nectar carrying capacity
h	Flower handling time
t(i, j)	Flight time between patches i and j
F <sub>i</sub>	Number of flowers in patch i
$I_i$	Replenishment interval for patch i
P(x)	Bee's foraging efficiency in foraging bout x
G(x)	Elapsed time on the global clock since foraging bout x began
$R_{\mathrm{full}}$	Reward (in nectar units) offered by a full flower
R <sub>empty</sub>	Reward (in nectar units) offered by an empty flower
Т	Total time spent observing in empirical study
$T_{B}$	Total time (in seconds) spent actively observing bee activity in empirical study
a	Proportion of array observed during an empirical study session

#### **Definitions**

Dry (D) Patch A patch of flowers that is droughted

Floral Catchment The set of patches representing the surrounding landscape external to

the sink and source populations.

HARVEST Harvesting Animal Reinforced Values and Estimates. A

Reinforcement Learning-based foraging model.

Omniscient Bee A HARVEST bee that is always aware of the true quality of patches in

the landscape

Performance The quantified foraging efficiency of a HARVEST bee, expressed in

terms of the amount of resource gathered divided by the time taken to

do so

Sacrificial Shield An array of resource sites whose genetic purity is sacrificed to

preserve the genetic purity of another population.

SWIPT System-wide inter-patch traffic. A measure of the level of movement

by bees on average within the foraging system.

Wet (W) Patch A patch of flowers that is kept healthy by being regularly watered

#### **Abbreviations**

% Percentage

μ Micro

AI Artificial Intelligence

ANN Artificial Neural Network

B. napus
BL Bombus lapidaries
BP Bombus pratorum
BT Bombus terrestris

D Dry

DEFRA Department for Environment, Food and Rural Affairs

EU European Union

GM Genetically Modified

h Hours

HARVEST Harvesting Animal Reinforced Values and Estimates
HOOFS Hierarchical Object Oriented Foraging Simulator

IBM Individual Based Model
IFD Ideal Free Distribution

IP Iconic Pattern

JST Job Search Theory

km Kilometre

1 Litre

LS Landscape-Scale

m Metre

MVT Marginal Value Theorem
OFT Optimal Foraging Theory
PMF Plant Molecular Pharming
RL Reinforcement Learning
RNEI Rate of Net Energetic Intake

s Seconds

S.E. Standard Error SS Sacrificial Shield

t.u. Time Unit

TDR Threshold Departure Rule

W Wet