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# **Urban Area Function Zoning Based on User Relationships in Location-based Social Networks**

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**ABSTRACT** With advanced development of Internet communication and ubiquitous computing, Social Networks are providing an important information channel for smart city construction. Therefore, analyzing Location-based Social Network is a very valuable work in achieving reasonable urban zoning. In Social Networks, a main purpose of prestige assessment is to extract influential users who are regarded as the key nodes for community detection from Onine Social Networks (OSNs). However, social relationships of users are rarely used to evaluate the popularity of physical locations and zone physical locations. In order to achieve urban area function zoning by evaluating the prestige of geographic regions based on user relationships in Location based Social Networks (LBSNs), this paper proposes a Prestige Density-Based Spatial Clustering of Applications with Noise algorithm (P-DBSCAN) by improving the existing DBSCAN algorithm. Specifically, the algorithm first calculates the centrality of users in the social network, and then converts the centrality of users into the location-centrality through the users' check-in data. After the centrality of each location is obtained, the discrete locations are clustered according to four constraints of the given radius. After clustering, the result of urban area function zoning can be achieved. Extensive experiments are conducted for demonstrating the effectiveness of our proposed algorithm in this paper. In addition, the visualization results reveal the correctness of our proposed approach.

**INDEX TERMS** Social network, Prestige assessment, Density clustering, Eigenvector centrality, Urban area function

#### I. INTRODUCTION

As an important task of urban construction, urban area function zoning, requires the urban area function to be consistent with the actual activities of people [1], [6]. With the rapid development of computer science and technology, OSNs have been growing from nothing to cover more and more potential application fields, in which LBSNs provide an effective way to link individual's activities to geographic regions. LBSNs have the following features: (1) allowing users to form their social networks according to social interactions; (2) allowing users to connect with places by checking in. Therefore, in this paper, we conduct prestige assessment of users according to their social relationships and then the prestige of user can be further obtained in different locations according to users' check-in data. After that, we zone urban area function according to prestige of locations [2].

As an important research topic in social network analysis, the major purpose of prestige assessment [7] is to find influential users from social networks. The influential users can be the key nodes for information diffusion and community detection [3]. There have been a number of relevant theoretical and empirical studies on the evaluation of social network prestige. Musial et.al [4] compared and summarized the user prestige assessment methods, such as Centrality Based on Node Degree [8], Eccentricity Centrality [9], Closeness Centrality [10], and Betweenness Centrality [11] which are commonly used in social network analysis. Particularly, the Eigenvector Centrality [12] is also an efficient approach for prestige evaluation. However, such prestige assessment only focuses on "user" without the influence of user's prestige on geographic regions. It limits the value and scope of applications enabled with prestige assessment results. In real life, we often describe a busy place according to the large flow of people. However, this is only a quantitative description, where the "quality" of users who have checked in here, is also an important factor for measuring the prestige of this place. In OSNs, the user's quality is thus characterized as the centrality value, in which the different types of centrality reflect the quality of the user's different aspects. Therefore, the prestige value of the entire geographical area can be evaluated by accumulating the "quantity" and "quality" of the users who checked in the area [27]. To address that issue, this paper conducts prestige assessment of locations on the basis of social network users' prestige assessment, including prestige assessment for discrete locations and geographic regions derived from density clustering [26].

As we known, density clustering using the DBSCAN algorithm can well divide many discrete locations into related geographic regions [5], [13]. Aiming to achieve the urban area function zoning, this paper pioneers a novel Prestige Density Based Spatial Clustering algorithm (P-DBSCAN) by modifying the existing DBSCAN algorithm [20]. The major contributions of this paper are summarized as follows:

- Transformation from user centrality to location centrality: A social network can be represented with multiple nodes (i.e., users) and edges which indicates the social interactions. Normally, a social network [14] is mathematically formalized as a graph G = (V, E) with V indicating the set of vertices and E referring to the set of relationships between vertices. In this paper, the centrality value of user  $V_i$  is denoted as  $UCV(V_i)$ , and the centrality value of location  $L_i$  is denoted as  $LCV(L_i) = \sum_{h=k}^{j} (UCV(V_h)) (V_j,...,V_k$  are the users who had checked in location  $L_i$ ).
- **Prestige Density based Spatial Clustering algorithm:** Our proposed P-DBSCAN algorithm has four requirements for center point selection: 1) the radius; 2) the requirement for prestige of the center point; 3) the requirement for the number of points around the center point; 4) and the requirement for the sum of prestige of the points around the center point. The outputs are the

location clustering results and the prestige of geographical area. That is to say, the clustering results are related not only to the distance between locations, but also to the prestige value.

• **Evaluation:** We conduct the experiments on a real location-based social networking dataset for validating the effectiveness of the proposed approach. The visualization results demonstrate that the clustering results are not only consistent with the real urban area function zoning, but also reflect the importance of each urban functional area.

The remainder of this paper is structured as follows. Section II overviews the related work. The preliminaries and problem statement are provided in Section III. Section IV proposes our approach for the addressed problem. The experimental results and discussions are presented in Section V. Section VI concludes this paper.

### **II. RELATED WORK**

In this section, we will overview the most related research to this work from the following two aspects: (1) Influential location in LBSNs; and (2) Density based clustering.

# A. INFLUENTIAL LOCATION IN LBSNS

Regarding to location promotion problem, Zhu et.al. [21] formalized it as an influence maximization problem in an LBSNs. They proposed two user mobility models, i.e., Gaussian-based and distance-based mobility models, to capture the check-in behavior of individual user in LBSNs, based on location-aware propagation probabilities. Hai et.al [22] proposed the PMNF model to capture human mobility and the IM greedy algorithms to maximize the influence spread of influential users. Their experiments validated that the PMNF model has covered important areas of human movement behavior. Wang et.al [23] first formulated the distance-aware influence maximization problem, then extracted a seed set that maximizes the expected influence over users who are more likely to be the potential customers of the promoted location. In one word, given a target location, their aim is to find the users that should be advertised to attract more visitors to this location. Doan et al. [24] evaluated the popularity ranks of locations based on the number of visitors. Aiming to find a single location which attracts most users, Zhou et al. [25] investigated the problem of choosing an optimal location for an event such that the event's influence can be maximized.

# B. DENSITY BASED CLUSTERING

Density clustering method has been widely used in network analysis and data mining, etc. It considers the internally continuous dense sample subset as the same type, and the representative algorithm is DBSCAN. DBSCAN algorithm first divides all sample points into center points and noncenter points, where the center points refer to those points within the radius r where the number of sample points is greater than k, where r and k are both parameters. If the distance between the two center points does not exceed r,

it is called the direct density reachable. The center point with multiple direct densities is called density reachable. A class cluster is formed when a center point set with a maximum density reachable is merged with the non-center points within the radius r of each center point. It can be seen that the center point sets between various clusters obtained by DBSCAN algorithm do not intersect, but the non-center point sets may intersect, and there may be some non-center points whose rradius does not contain any center points, which is regarded as noise. Therefore, DBSCAN algorithm allows class cluster overlap and some points do not belong to any class cluster, which is an advantage that most other clustering algorithms do not have. The disadvantage of DBSCAN algorithm is that it utilizes a uniform scale r and k to measure all class clusters, which is often inappropriate [19]. Therefore, an improved version of the OPTICS [15] algorithm has been proposed, which sets the radius r as a flexible parameter to be adjusted by the algorithm itself, but it is ideologically the same as DBSCAN. However, the clustering result obtained by this improved algorithm is still only related to the distance between sample points, and our proposed P-DBSCAN algorithm increases the judgment condition of the center point, so that the clustering result is also related to the attribute (prestige of location) of the sample points.

#### **III. PRELIMINARIES AND PROBLEM STATEMENT**

This section firstly introduces the preliminaries on location social network and DBSCAN algorithm. Then, the problem of urban area function zoning based on user relationships in location-based social networks is formally defined.

Definition 1: (Location-based Social Network) [16], [17] A location-based social network can be represented as a 3-tuple G=(V, E, C), where V is the set of nodes (i.e., users), and E is the set of edges which indicates the social connections between users, and C is the users' check-in data set, each of these pieces of data records a user checking in at a certain time and place.

Figure 1 depicts an architecture of Location-based Social Network that are social networks using GPS features to locate you and that let you broadcast your location and location-tagged media content, such as photos, video, and texts from your mobile device. Therefore, this architecture contains two layers: (1) OSNs Layer: in this layer, users form their social networks according to interactions in LBSNs; (2) Physical Location Layer: mobile users who hold their mobile devices can broadcast their location by checking-in and checking-out with location-based services apps.

Overall, the physical location is composed of the instant location of a mobile user at a given timestamp and the location history that a mobile user has accumulated in a certain period. Further, the interdependency includes not only that two mobile users co-occur in the same physical location or share similar location histories but also the knowledge, e.g., common interests, behavior, and activities, inferred from an user's location and location-tagged data [28].

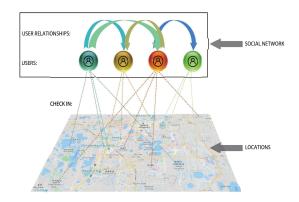


FIGURE 1. Architecture of Location-based Social Network.

**DBSCAN algorithm:** It is a density-based clustering algorithm based on high-density connected regions, which can divide regions with sufficient high-density into clusters and find clusters of arbitrary shapes in noisy data. This algorithm needs to select a distance for measuring. For the data set to be clustered, the distance between any two points reflects the density between points, indicating whether points and points can be clustered in the same class. Because the DBSCAN algorithm is difficult to define the density of high-dimensional data, the points in two-dimensional space can be measured by Euclidean distance.

DBSCAN algorithm requires two input parameters: one parameter is radius (Eps), which represents the range of circular neighborhood centered on a given point P; the other parameter is the minimum number of points in the neighborhood centered at point P (MinPts). Point P is called the center point if the number of points in the neighborhood with point P as the center and radius of Eps is no less than MinPts [18]. Unlike existing algorithms, the modified DBSCAN algorithm requires four input parameters. Besides Eps and MinPts, we add two constraints: the requirement for the center point prestige value, and the requirement for the sum of prestige value of the points around the center point. After the center points selected, the center points that can be connected are divided into a group and outliers are obtained according to the set of center points obtained and the value of radius Eps. It puts each group of center points and the points whose distance from the center point is less than the radius Eps into a cluster. Consequently, it completes the cluster division.

Figure 2 shows an example of an existing DBSCAN algorithm, where the clustering result is only related to the distance of points.

Problem 1: (**Urban Area Function Zoning based on User Relationships in Location-based Social Networks**) Figure 3 shows the map of Orlando, Florida, USA presented

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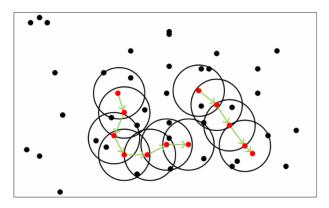


FIGURE 2. An example of DBSCAN algorithm.

by Google map<sup>1</sup>. This paper will cluster the locations of Orlando and evaluate its geographical prestige. The popularity ratings are based on public location-based social networks data sets that are available from Stanford university <sup>2</sup>. The social network among users active in Orlando is G(V, E), where V is the node set, representing all users in the social network, and E is the edge set. If there is an edge $(V_1, V_2)$  in E, it means there is a connection between these two users. Another user's check-in data table Q contains the time and place the user checked in. The user's reputation value can be calculated via social network G, and the user's reputation can be assigned to the location via Q. After clustering the locations, the prestige of the geographical area can be further calculated.

Gowalla is a location-based social network where users share their location by checking in. The user's relational network is undirected, consisting of 196,591 nodes and 950,327 edges. Between February 2009 and October 2010, a total of 644,890 user check-ins are collected. In this paper, we only use the check-in data within Orlando city (longitude -81.15° to -81.65°, latitude 28.3° to 28.7°). The users' check-in data, named *gowalla\_totalcheckins.txt*, is shown in Figure 4. For each behavior, one check-in data is user id, check-in time, check-in location latitude, check-in location longitude, and check-in location id from left to right. As shown in Figure 5, each behavior has two associated users'id, representing one edge of the relational network.

#### **IV. PROPOSED APPROACH**

In this section, we introduce how to implement the urban area function zoning of Orlando based on user relationships in LBSNs. The process of implementation is shown in Figure 6, which is composed of five steps: (1) check-in data filtering (Red module); (2) user relationship network filtering (Yellow module); (3) calculating the node centrality of location (Blue module); (4) calculating the eigenvector centrality of location (Green module); (5) density clustering (Purple modules).

#### Step 1: Check-in data filtering

<sup>1</sup>https://www.google.com/maps/place/orlando.html <sup>2</sup>http://snap.stanford.edu/data/loc-Gowalla.html

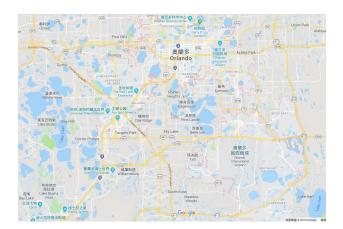


FIGURE 3. The map of Orlando, Florida, USA.

1	0	2010-10-19T23:55:27Z	30.2359091167	-97.7951395833	22847
2	0	2010-10-18T22:17:43Z	30.2691029532	-97.7493953705	420315
3	0	2010-10-17T23:42:03Z	30.2557309927	-97.7633857727	316637
4	0	2010-10-17T19:26:05Z	30.2634181234	-97.7575966669	16516
5	0	2010-10-16T18:50:42Z	30.2742918584	-97.7405226231	5535878
6	0	2010-10-12T23:58:03Z	30.261599404	-97.7585805953	15372
7	0	2010-10-12T22:02:11Z	30.2679095833	-97.7493124167	21714
8	0	2010-10-12T19:44:40Z	30.2691029532	-97.7493953705	420315
9	0	2010-10-12T15:57:20Z	30.2811204101	-97.7452111244	153505
	0	2010-10-12T15:19:03Z	30.2691029532	-97.7493953705	420315
11	0	2010-10-12T00:21:28Z	40.6438845363	-73.7828063965	23261
	0	2010-10-11T20:21:20Z	40.74137425 -73	.9881052167 169	07
13	0	2010-10-11T20:20:42Z	40.741388197	-73.9894545078	12973
14	0	2010-10-11T00:06:30Z	40.7249103345	-73.9946207517	341255
15	0	2010-10-10T22:00:37Z	40.729768314	-73.9985353275	260957
16	0	2010-10-10T21:17:14Z	40.7285271242	-73.9968681335	1933724
17	0	2010-10-10T17:47:04Z	40.7417466987	-73.993421425	105068
18	0	2010-10-09T23:51:10Z	40.7341933833	-74.0041635333	34817
19	0	2010-10-09T22:27:07Z	40.7425115937	-74.0060305595	27836
	0	2010-10-09T21:39:26Z	40.7423961659	-74.0075433254	15079
21	0	2010-10-09T21:36:05Z	40.7423961659	-74.0075433254	15079
22	0	2010-10-09T21:05:23Z	40.7358847426	-74.0049684048	22806
23	0	2010-10-09T20:55:47Z	40.7275253534	-73.9853990078	1365909
24	0	2010-10-09T01:37:03Z	40.7568799674	-73.9862251282	11844
	0	2010-10-08T21:48:37Z	40.7074172208	-74.0113627911	11742
26	0	2010-10-08T21:45:48Z	40.7071727167	-74.0105454333	19822
27	0	2010-10-08T21:43:52Z	40.7070708167	-74.0119528667	15169
28	0	2010-10-08T21:43:02Z	40.705823135	-73.9966964722	11794
29	0	2010-10-08T19:28:36Z	40.7693780407	-73.9630830288	1567837
	0	2010-10-08T17:24:27Z	40.7808054632	-73.9764726162	35513

FIGURE 4. The sample of Gowalla totalcheckins.txt.

- Go	walla	a_edges.txt🖾 🛛	🔚 Gowall	a_edges.t	xt🖾
1	0	1	605792	12060	92486
2	0	2	605793	12060	92487
3	0	3	605794	12060	92488
4	0	4	605795	12060	92489
5	0	5	605796	12061	203
6	0	6	605797	12061	483
7	0	7	605798	12061	1545
8	0	8	605799	12061	3584
9	0	9	605800	12061	3824
10	0	10	605801	12061	9747
11	0	11	605802	12061	12101
12	0	12	605803	12061	15377
13	0	13	605804	12061	24641
14	0	14	605805	12061	28794
15	0	15	605806	12061	31623
16	0	16	605807	12061	36417
17	0	17	605808	12061	36434
18	0	18	605809	12061	36789
19	0	19	605810	12061	68785
20	0	20	605811	12061	76609
21	0	21	605812	12062	203
22	0	22	605813	12062	1413
23	0	23	605814	12062	1431
24	0	24	605815	12062	2149
25	0	25	605816	12062	3587
26	0	26	605817	12062	3702
27	0	27	605818	12062	6536
28	0	28	605819	12062	12033
29	0	29	605820	12062	44447
30	0	30	605821	12062	47469

**FIGURE 5.** The sample of *Gowalla\_edges.txt*.

By invoking Algorithm 1, this step works as follows: It opens and reads file *Gowalla\_totalCheckins.txt* line by line, and converts each line into a list named *check\_out*[]

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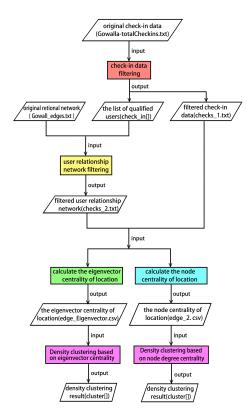


FIGURE 6. The framework of our proposed approach.

(Line 2). Then it checks whether the second and third item of  $check\_out[]$  (the latitude and longitude value of the check-in place) meet the requirements. If it matches, the line is written to the newly created document  $checks\_1.txt$  (as shown in Figure 7), and the first item of  $check\_out[]$  (user id number) added to the list  $check\_in[]$  (Lines 3-5).

Algorithm 1 Check-in data filtering algorithm.

#### Input:

Original check-in data(*Gowalla\_totalCheckins.txt*) **Output:** 

List of qualified users(*checks\_in*[]), filtered check\_in data(*checks\_1.txt*)

- 1: begin
- 2: for each line in *Gowalla\_totalCheckins.txt*

3: if this line of check-in data in Orlando

- 4: write this line into  $checks\_1.txt$
- 5: *check\_in.append*(the user of this line)
- 6: **end**

#### Step 2: User relationship network filtering

This step works by invoking Algorithm 2: this step opens and reads file  $Gowalla\_edges.txt$  line by line, and converts each line into a list named  $select\_out[]$  (Line 2). If both the zeroth and first item of  $select\_out[]$  are contained in  $check\_in[]$  (user a and user b have both been checked in the scope), that line is written to the document  $checks\_2.txt$ 

🗄 che		1. txt🖾				
1					-81.2970256805	
2					-81.3075828552	
3	41	2010-0	7-16T17:38:21Z	28.4728316363	-81.473171711 :	054383
4	41	2010-0	7-16T16:09:46Z	28.4720016952	-81.4735257626	1054228
5	41	2010-0	7-16T15:26:242	28.4728009852	-81.4728847146	1054463
6	41	2010-0	7-16T15:00:41Z		-81.4728927612	668177
7	41	2010-0	7-16T14:47:12Z	28.4705705032	-81.4699074626	222926
8	41	2010-0	7-16T14:25:27Z	28.4714775333	-81.4687824167	42894
9	41	2010-0	7-16T12:59:20Z	28.4719168145	-81.4695239067	24455
10	41	2010-0	7-16T12:43:57Z	28.4752931276	-81.4675068855	15400
11	41	2010-0	7-16T10:39:55Z	28.4562827114	-81.3089124197	927571
12	41	2010-0	7-16T03:44:20Z	28.4311095989	-81.3075828552	758476
13	69	2010-1	0-20T01:47:052	28.3872285337	-81.4924407005	312303
14	69	2010-1	0-20T01:46:46Z	28.3875494505	-81.4930844307	589694
15	69	2010-1	0-20T00:53:02Z	28.3709891136	-81.547306627 5	582694
16	69	2010-1	0-20T00:52:31Z	28.3706166167	-81.54684875 89	1071
17	69	2010-1	0-19723:48:372	28.3718139468	-81.5494000912	1122866
18	69	2010-1	0-19T23:48:07Z	28.3716251444	-81.5493893623	5105013
19	69	2010-1	0-19T23:47:19Z	28.370592625	-81.5470142663	123925
20	69	2010-1	0-19T23:47:00Z	28.3708269333	-81.54702875 65	50212
21	69	2010-1	0-19723:12:232	28.3705186833	-81.5469431833	14686
22	69	2010-1	0-19723:11:492	28.3676885366	-81.5481448174	14573
23	69	2010-1	0-19723:11:212	28.3684028333	-81.5474620167	582857
24	69	2010-1	0-19T23:10:50Z	28.371400941 .	-81.5475788713	4568
25	69	2010-1	0-19722:48:252	28.3699353474	-81.5464282036	14571
26	69	2010-1	0-19722:47:252	28.3698409446	-81.5494537354	582787
27	69	2010-1	0-19T22:46:25Z	28.3704073605	-81.5520823002	14586
28	69	2010-1	0-19T22:46:04Z	28.3698031834	-81.5531659126	243909
29	69	2010-1	0-19722:45:412	28.3678773461	-81.5493679047	14574
30	69	2010-1	0-19722:45:252	28.3688166682	-81,5530318022	3530357

FIGURE 7. The sample of *checks\_1.txt*.

📄 che	cks_	2. txt🖂	🔚 che	cks_2	2. txt🖂
1	41	98	175	307	9427
2	41	582	176	307	9523
3	41	3870	177	307	9568
4	41	5670	178	307	9669
5	41	5736	179	307	9682
6	41	5742	180	307	9702 9874
7	41	5743	182	307	10310
8	41	5759	183	307	10385
9	69	307	184	307	10388
			185	307	10426
10	69	7202	186	307	10760
11	69	7211	187	307	10792
12	69	7212	188	307	10850
13	98	41	189	307	10861
14	98	138	190	307	11036
15	98	6112	191	307	11043

FIGURE 8. The sample of *checks\_2.txt*.

(Lines 3-4) (as shown in Figure 8).

Input	
0	riginal relational network(Gowalla_edges.txt), list of
qu	alified users(check_in[])
Outpu	it:
Fi	ltered user relationship network(checks_2.txt)
1: <b>be</b>	egin
2: <b>fo</b>	<b>r</b> each line in <i>Gowalla_totalCheckins.txt</i>
3:	if both users of this line in <i>check_in</i> []
4:	write this line into <i>checks_2.txt</i>
5: <b>en</b>	ıd
Ste	p 3: Calculating the node centrality of location
This	s step works as follows: we take checks_2.txt and
check	$s_{1.txt}$ as inputs of this step, then we create a

This step works as follows: we take  $checks\_2.txt$  and  $checks\_1.txt$  as inputs of this step, then we create a file named  $edge\_2.csv$  with four columns for "local\_id", "longitude", "latitude" and "degree\_local". After that, we calculate the node degree centrality of users according to  $checks\_2.txt$  (Line 2 in Algorithm 3), and assign the node degree centrality of users to check-in locations according to  $checks\_1.txt$ . At last, the location data is stored in  $edge\_2.csv$  (as shown in Figure 9), and each line of data contains four components: location id, location longitude value, location latitude value, and node degree centrality of location (Lines 3-5 in Algorithm 3).

#### Step 4: Calculating the eigenvector centrality of loca-

**Algorithm 3** Calculating the node centrality of location algorithm.

### Input:

Filtered user relationship network( $checks_2.txt$ ), filtered check\_in data( $checks_1.txt$ )

# **Output:**

Node centrality of location(edge\_2.csv)

- 1: begin
- 2: calculate the node degree centrality of users

3: for each location

- 4:  $LCV(L_i) = \sum_{h=k}^{j} (UCV(V_h)) \quad (V_j,...,V_k \text{ are the users who had checked in location } L_i)$
- 5: write this line into  $checks_2.txt$
- 6: **end**

	A	В	С	D
1	local_id	longitude	latitude	degree_local
2	469336	-81. 297026	28. 4294491	76
3	758476	-81. 307583	28. 4311096	1625
4	1054383	-81. 473172	28. 4728316	106
5	1054228	-81. 473526	28. 4720017	169
6	1054463	-81. 472885	28. 472801	204
7	668177	-81. 472893	28. 4703512	26
8	222926	-81. 469907	28. 4705705	89
9	42894	-81. 468782	28. 4714775	152
10	24455	-81. 469524	28. 4719168	297
11	15400	-81. 467507	28. 4752931	381
12	927571	-81. 308912	28. 4562827	19

FIGURE 9. The sample of *edge\_2.csv*.

### tion

In this step, user's node degree centrality is taken as the initial value to calculate user's eigenvector centrality. After that, we assign the eigenvector centrality of users to check-in locations by the same way we carried out in the previous step. At last, the location information data is stored in *edge\_Eigenvector.csv*.

# Step 5: P-DBSCAN based clustering

As shown in Algorithm 4, edge\_2.csv or

 $edge\_Eigenvector.csv$  is the input of this step, and we store the file contents in data[] as a list. Then we select center points from data[] and store it in the list  $center\_p[]$  (Lines 3-5). After center points selected, the center points that can be connected are divided into a group. We put each group of center points and the points whose distance from the center point is less than the radius into a cluster. Thus complete the clustering division (Lines 6-7). And the total prestige value of the region is obtained by adding the prestige values of all locations in same cluster.

#### **V. EXPERIMENTS**

This section mainly carries out the experiments and evaluates the proposed approach. All the experiments are implemented on a quad-core computer with 2.50-GHZ and 8G memory. Algorithm 4 P-DBSCAN based clustering algorithm.

#### Input:

Node centrality of location(*edge\_2.csv*), or, eigenvector centrality of location(*edge\_Eigenvector.csv*)

# **Output:**

- Density cluster result(clusters[])
- 1: data[]=edge\_2.csv or edge\_Eigenvector.csv
- 2: begin
- 3: for each line in data
- 4: **if** the location in this line meets the four constraints
- 5: *center\_p.append*(this line)
- 6: def *divi\_centerP*(data, eps, minPts, deg1, deg2):
- 7: def *add\_otherP*(data, eps, minPts, deg1, deg2):
- 8: **end**

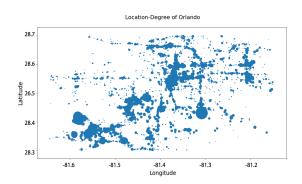


FIGURE 10. The visualization of file *edge\_2.csv*.

#### A. VISUALIZATION OF EXPERIMENTAL RESULTS

In order to better exhibit the experimental results, we employed the bubble chart as the visualization of experimental results.

Figure 10 shows the visualization result of *edge\_2.csv*, each circle in the figure represents a place in Orlando, and the larger the circle's radius, the higher the prestige value of the place.

When calculating the eigenvector centrality, we need to multiply the adjacency matrix and the initial vector many times, since the elements in the matrix and vector are both positive, the value obtained by multiple times multiplication is very large, and the output of the final result needs to be scaled down by  $10^{61}$  times. And Figure 11 is the visualization result of *edge\_Eigenvector.csv*.

According to the clustering result, list *clusters*[], obtained in step 5, we respectively visualize the results of density clustering based on node degree centrality and density clustering based on eigenvector centrality (as shown in Figure 12 and Figure 13).

#### **B. ANALYSIS OF EXPERIMENTAL RESULTS**

In this experiment, more than 5,000 locations in Orlando are divided into 7 zones. By comparing with the real  $map^3$  (Figure 3), we found out the important locations in

<sup>3</sup>https://www.google.com/maps/place/orlando.html

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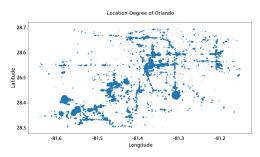


FIGURE 11. The visualization of file *edge\_Eigenvector.csv*.

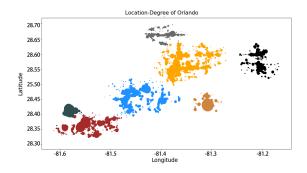


FIGURE 12. Clustering result based on node centrality of location.

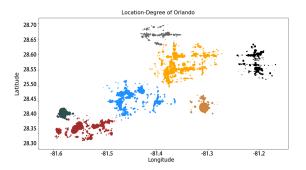


FIGURE 13. Clustering result based on eigenvector centrality of location.

each zone and calculated the total value of each zone (as shown in Figure 14). Figures 15 and 16 show the percentage of prestige for area functions (i.e., the popularity of area functions) with two approaches. Apparently, it is found that there exists a little bit difference in the relative prestige between approaches.

The running time of each step is shown in Table 1:

TABLE 1. Running Time of each Part of the Process

Process step	Step 1	Step 2	Step 3
Running time	100.31s	461.45s	45.72s
Process step	Step 4	Step 5	Step 5
		(node degree	(eigenvector
		centrality)	centrality)
Running time	481.85s	216.15s	218.88s

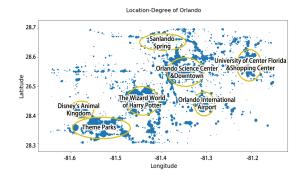


FIGURE 14. The important functional point-of-interests in each zone.

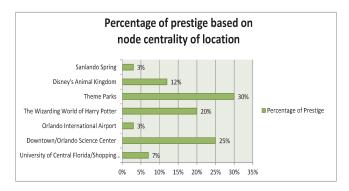


FIGURE 15. Prestige assessment result based on node centrality of location.

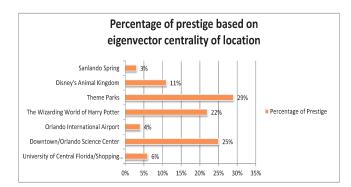


FIGURE 16. Prestige assessment result based on eigenvector centrality of location.

#### C. ANALYSIS OF INPUT CONDITION

The key problem to be solved in this paper is to use the P-DBSCAN algorithm to evaluate the popularity of geographic regions and zone them based on user's prestige.

The input of the P-DBSCAN algorithm is the location information data set. We have the following four requirements: the given radius (**Requirement 1**), the requirement for the center point reputation value (**Requirement 2**), the requirement for the number of locations around the center point (**Requirement 3**), and the requirement for the sum of the location reputation value around the center point (**Requirement 4**); and the output is the result of urban area function zoning and geographical region prestige value.

Let us take the regional prestige evaluation based on node

degree centrality as an example, the locations are divided into 7 clusters, which is consistent with the location relationship in the actual map. At this time, the given radius is 0.022 longitude and latitude, at least 160 points within the radius are required, the site reputation value is required to be at least 30, and the sum of the surrounding sites reputation value is required to be at least 2000. We use the control variable method to study the relationship between each input value and the clustering division result, change the value of one constraint condition and keep the other three input values unchanged, and obtain the relationship between each input value and the number of clustering and the number of center points (as shown from Table 2 to Table 5).

 TABLE 2. Requirements for the sum of reputation values around the central point

Requirement 4	0	2000	3000	5000	7000	9000
# of center points	2134	2134	2131	2090	1957	1586
# of clusters	7	7	7	6	7	5

 TABLE 3.
 Central point reputation requirements

Requirement 2	0	30	50	100	200	500
# of center points	2134	2134	1511	419	176	56
	7	7	9	11	12	3

TABLE 4. Requirements for the number of locations around the central point

Requirement 3	60	100	160	200	300	500
# of center points	2398	2327	2134	1984	1035	94
	7	8	7	8	3	2

TABLE 5. Requirements for radius

Requirement 1	0.01	0.02	0.022	0.03	0.05	0.1
# of center points	983	2064	2134	2393	2613	2688
♯ of clusters	10	9	7	7	2	1

It can be seen that the higher the requirement of the constraint condition, the fewer points meet the center point condition. When the center point becomes small, the number of clustering may increase or decrease. The increase is caused by the disappearance of the center point acting as the "bridge" in the original cluster, which results in the splitting of the original cluster. The reduction is due to the disappearance of a large number of center points and the disappearance of the entire cluster.

In fact, the relationship between the input and output of the P-DBSCAN algorithm can be viewed as a function with four independent variables and two dependent variables. Since such a function cannot be directly represented with a graph, the above tables only partially reflect the relationship between the input and output of the algorithm.

#### **VI. CONCLUSIONS**

This paper aims to evaluate the reputation of geographical areas in reality based on social networks, so as to provide a support for the actual urban planning and supporting facilities construction. We propose a modified DBSCAN algorithm, termed P-DBSCAN which is a novel Prestige Density Based Spatial Clustering algorithm. The algorithm first calculates the centrality of users in the social network, and then converts the centrality of users into the location-centrality through the user check-in data. After obtaining the centrality of each location, the discrete locations are clustered according to the four constraints of the given radius. After clustering, the result of urban area function zoning can be achieved. The reputation of the interior points of the geographical area divided is the total reputation of the geographical area. In order to test the performance of the proposed algorithm, we also used the control variable method to study the influence of each constraint condition on the final output. Experimental results show that the output of our algorithm is consistent with the real map.

In this paper, we have completed the geographical area prestige assessment, however this is based on a relatively simple static social network. The original check-in data set contains user check-in time information, which is not utilized by our algorithm. In the subsequent algorithm improvement, it can be considered to construct a dynamic social network by using the time information in the check-in data, and change the user's prestige from a constant to a dynamic function, so as to change the location reputation evaluation from static to dynamic.

In addition, with the rapid growth of various online social networking services, the types of social networks are increasingly diversified. In this paper, we use only data from the location-based social networking service Gowalla. From a development point of view, we plan to conduct a prestige assessment based on data from online platforms in other potential fields to verify the applicability and universality of our approach.

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