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## 3D animal camouflage

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1 **Abstract**

2

3 Camouflage is a fundamental way for animals to avoid detection and recognition. While depth  
4 information is critical for object detection and recognition, little is known about how camouflage  
5 patterns might interfere with the mechanisms of depth perception. We reveal how many common  
6 camouflage strategies could exploit 3D visual processing mechanisms.

7

8

9 **Main text**

10

11 **Animals live in a 3D world**

12

13 Animals exist in a 3D world, and **depth** (see Glossary) information is essential for judging the  
14 location, shape and orientation of objects. As a result, visual systems have evolved multiple ways  
15 to recover depth information. In the 3D arms race between predators and their prey, depth  
16 perception is thought to have evolved for camouflage breaking, so animal patterning must have  
17 evolved to conceal valid depth cues. Recent studies have revealed some remarkable ways in which  
18 non-human animals perceive depth [1, 2]. However, the role of depth information in prey  
19 camouflage strategies remains poorly understood. Here we examine how common types of  
20 camouflaging colouration may function to manipulate the viewer's mechanisms of depth  
21 perception.

22

23 Animals can perceive depth using **absolute depth** cues such as **binocular disparity** and  
24 **accommodative (focus) effort**, but most 3D information is obtained from **relative depth** cues.  
25 Pictorial depth cues such as object shading and **occlusion** could readily defeat the viewer's  
26 mechanisms of depth perception, because they exploit the laws of physics and/or use prior  
27 knowledge of visual scenes. Human observers, for example, judge distance based on an object's  
28 brightness (close objects are often brighter, and brighter, otherwise equivalent, objects are  
29 perceived as closer). Visual systems also assume that light comes from above (because sunlight is  
30 generally from overhead), and that, consequently, 3D objects produce a **self-shadow**. This  
31 correspondence between the direction of illumination and an object's self-shadows provides  
32 important information about object depth, location, distance and shape.

33

34 **Countershading colouration** is thought to reduce or eliminate self-shadows to enhance  
35 camouflage (**Fig. 1**). Countershading increases prey survival when the shading is optimised for the  
36 lighting conditions [3]. However, there is scant evidence that countershading interferes with 3D  
37 shape recovery in non-humans. A simpler explanation is that because visual systems detect  
38 objects on the basis of contrast, countershading may reduce detectability by reducing contrast  
39 across the body, or by reducing contrast at the body edges [4]. This could be particularly relevant  
40 when prey are viewed from a distance, where subtle depth cues are less critical than reduced  
41 visibility owing to contrast.

42

43 Non-human animals can use self-shadows for shape perception. European cuttlefish (*Sepia*  
44 *officinalis*) may exploit this when resting upon backgrounds with depth cues, by creating  
45 camouflage colouration that mimics self-shadows present on 3D objects in the background [5].  
46 Cuttlefish are not simply adjusting their colouration in response to background luminance; when  
47 placed on 3D backgrounds they displayed a unique colour pattern which is never expressed in  
48 response to the equivalent 2D visual cues [6]. Intriguingly, this body pattern produces the illusion  
49 of depth to the human visual system [6], suggesting that cuttlefish may deceive their predators  
50 using patterning that resembles the 3D geometry of the background.

51

52 Animal patterning could produce **pictorial depth cues** in the same way that artists use shading to  
53 generate perceived depth on a 2D canvas. This could interfere with the viewer's mechanisms of  
54 depth perception in four (non-mutually exclusive) ways. Firstly, pictorial depth cues may mimic the  
55 visual information in a natural scene so that the luminance properties of the body surface  
56 correspond with the luminance profile produced by the 3D background (Fig. 2a). Secondly,  
57 pictorial depth cues could generate a percept of three-dimensionality (**illusory depth**) allowing  
58 the patterning to resemble 3D objects in the background (Fig. 2b) [6]. Thirdly, animal body  
59 patterning could produce **visual texture** that mimics the surfaces of inedible objects for  
60 **masquerade** (Fig. 2c). Fourthly, pictorial depth cues may disrupt the continuity of the body surface  
61 to prevent the recognition of an object as a whole (Fig. 2d). For example, surface-specific changes  
62 in luminance could produce the illusion of a sloped surface, while sharp transitions in contrast  
63 could produce strong edges that segment the body into apparent discontinuous surfaces [7]. Edges  
64 can also cause illusory effects such as the Cornsweet illusion, which in primates and honeybees,  
65 causes strong differences in perceived brightness between adjoining regions, even if those regions  
66 are identical in luminance [8].

67

68 There are a number of visual processing mechanisms that pictorial depth cues could potentially  
69 exploit. **Enhanced edges** excite the visual system's edge detectors, stimulating a stronger signal  
70 than the body boundary, leading to incorrect **image segregation** [7]. However, it is also possible  
71 that such patterns may create new contours that form closed shapes, that would not normally  
72 signal the shape of the animal. Markings that disrupt surface continuity by producing illusory  
73 depth are likely to reduce **perceptual grouping** of the whole animal shape, that may be stronger  
74 than when considering the 2D effects of **disruptive colouration** (i.e. **false edges**) alone. In human  
75 vision, shading gradients and edges (among other cues) are a powerful cue for depth perception,  
76 and edges that are closer in luminance to the object tend to be grouped with the object rather  
77 than the background [9].

78

79 Binocular overlap is common among vertebrates, and depth perception using **stereopsis** allows  
80 predators to judge the distance of prey to increase their strike accuracy. Praying mantises  
81 (*Sphodromantis lineola*) were fitted with miniature glasses permitting 3D displays (with a different  
82 coloured filter over each eye) and presented with coloured images (anaglyphs) that generate a  
83 **percept** of prey distance [2]. Mantises altered their striking behaviour according to perceived  
84 depth, but this was not based on luminance correlations in the two images, as in vertebrates, but  
85 on the relationship between two areas defined by common motion relative to the background,  
86 overcoming uncorrelated luminance textures which defeat stereopsis in humans [2]. Cuttlefish  
87 also use binocular stereopsis, placing themselves in an optimal position prior to attacking prey [1],  
88 but the mechanisms are different to those in mantises, which are only able to obtain stereoscopic  
89 depth information when prey targets are in motion [2].

90

91 Stereopsis has been argued to assist with image segregation, because recognition of intrinsic  
92 borders aids segmentation of image regions, while recognition of extrinsic borders facilitates  
93 grouping [10]. Camouflage strategies that defeat image segregation, such as disruptive  
94 colouration, are therefore excellent candidates for defeating stereopsis. Binocular disparity  
95 facilitates detection of prey with disruptive patterning by aiding the discrimination of false edges  
96 from the real object boundaries [11]. Human participants asked to locate snake images of targets  
97 as if viewed separately for each eye (monoscopic trials) or by both eyes simultaneously  
98 (stereoscopic trials), found targets with enhanced edges harder to detect, but only when viewed  
99 by one eye, confirming that stereoscopic vision may facilitate detection of camouflaged prey [11].

100  
101 Pictorial depth cues such as enhanced edges take advantage of the viewer's ability to resolve  
102 depth using monocular cues (e.g. shading, texture). In experiments with human observers, targets  
103 with enhanced edges were deemed to have more depth than the background, and were  
104 particularly hard to detect when the background contained **cast shadows** [12]. These findings  
105 suggest that in the context of human vision, enhanced edges impede object detection by  
106 interfering with perceptual grouping [12]. Importantly, work with human observers suggests that  
107 multiple sources of depth information (i.e. binocular and monocular) can be integrated during  
108 visual search [11].

109  
110 Our understanding of how predators perceive depth cues, and how prey colouration exploits these  
111 mechanisms of visual processing to enhance camouflage, has only just begun. Most animals use  
112 multiple cues to perceive depth, but it is unclear how this information is combined into a single  
113 depth estimate. Many fundamental questions about 3D camouflage remain. Can pictorial depth  
114 cues improve **background matching**, and over what viewing distances is this strategy successful?  
115 Addressing these questions requires novel approaches for measuring depth perception in non-  
116 human animals, but would greatly enhance our understanding of animal camouflage.

117  
118  
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126 **Glossary**

127

128 **Absolute depth:** A measure of the actual distance between the observer and the object, based on  
129 cues such as binocular convergence and accommodation.

130

131 **Accommodative effort:** Use of the intra-ocular muscles to change the plane of focus of the eye's  
132 lens.

133

134 **Background matching:** Body colouration that generally matches the colour, luminance and pattern  
135 of the background.

136

137 **Binocular disparity:** Differences in the position of the retinal images of objects in the left and right  
138 eyes, due to the separation of the eyes.

139

140 **Cast shadows:** Shadow produced by an object and projected onto another surface (e.g. another  
141 object, the substrate).

142

143 **Countershading colouration:** Describes the ubiquitous phenomenon whereby animals tend to be  
144 most darkly coloured on the surface (usually the dorsal) that receives the most light.

145

146 **Depth:** The measurement or perception of the relative distances between an observer and the  
147 objects in a scene. This includes information on the distance, spatial arrangement and distance to  
148 parts (shape or depth variation) of an object as viewed by the observer.

149

150 **Disruptive colouration:** A set of markings that create the appearance of false edges and  
151 boundaries, hindering detection or recognition of the body outline.

152

153 **Enhanced edges:** Type of colour pattern where the borders of colour patches are accentuated, so  
154 that light patches have lighter edges, and dark patches have even darker edges.

155

156 **False edges:** Patterns that create the appearance of false boundaries, making the real outline of  
157 the body harder to detect and recognise.

158

159 **Illusory depth:** The perception of distance, spatial arrangement or shape, that does not  
160 correspond to the physical dimensions arising from the actual visual scene.  
161

162 **Image segregation:** A high-level feature integration used to determine which parts of an object  
163 form a whole by separating regions according to perceived contours or boundaries.  
164

165 **Masquerade:** Resemblance of an organism to an object of no inherent interest to the observer,  
166 such as an inedible object.  
167

168 **Occlusion:** Where the edges of one object are partially obscured by another, giving information on  
169 relative distance and order (e.g. whole objects are in front of/closer than obscured objects).  
170

171 **Perceptual grouping:** Determination of which component parts belong to a 'whole'.  
172

173 **Percept:** Representation of the external world created by the sensory system, which is then  
174 interpreted using rules or knowledge about the world.  
175

176 **Pictorial depth cues:** Patterns such as surface shading, enhanced edges and texture gradients,  
177 which mimic the properties of visual scenes to produce apparent changes in depth where none  
178 exist.  
179

180 **Relative depth:** Perception of the relative spatial relationships among different objects (e.g. order,  
181 separation), or between parts of the same object (e.g. object shape) without knowing the actual  
182 distance from the observer.  
183

184 **Self-shadow:** A shadow that is produced on the occluding object itself.  
185

186 **Stereopsis:** The experience of depth that is obtained as a result of combining the visual  
187 information received from two eyes.  
188

189 **Surface relief:** The physical geometry of a surface.  
190

191 **Visual texture:** An ensemble of image elements that conveys the properties of a much larger  
192 collection of images, allowing recognition of a material (e.g. glass, wood, plastic).  
193  
194  
195  
196

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224 edges and creating pictorial relief. *Scientific Reports* 6 (1), 38274.

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226

227 **Figure captions**

228

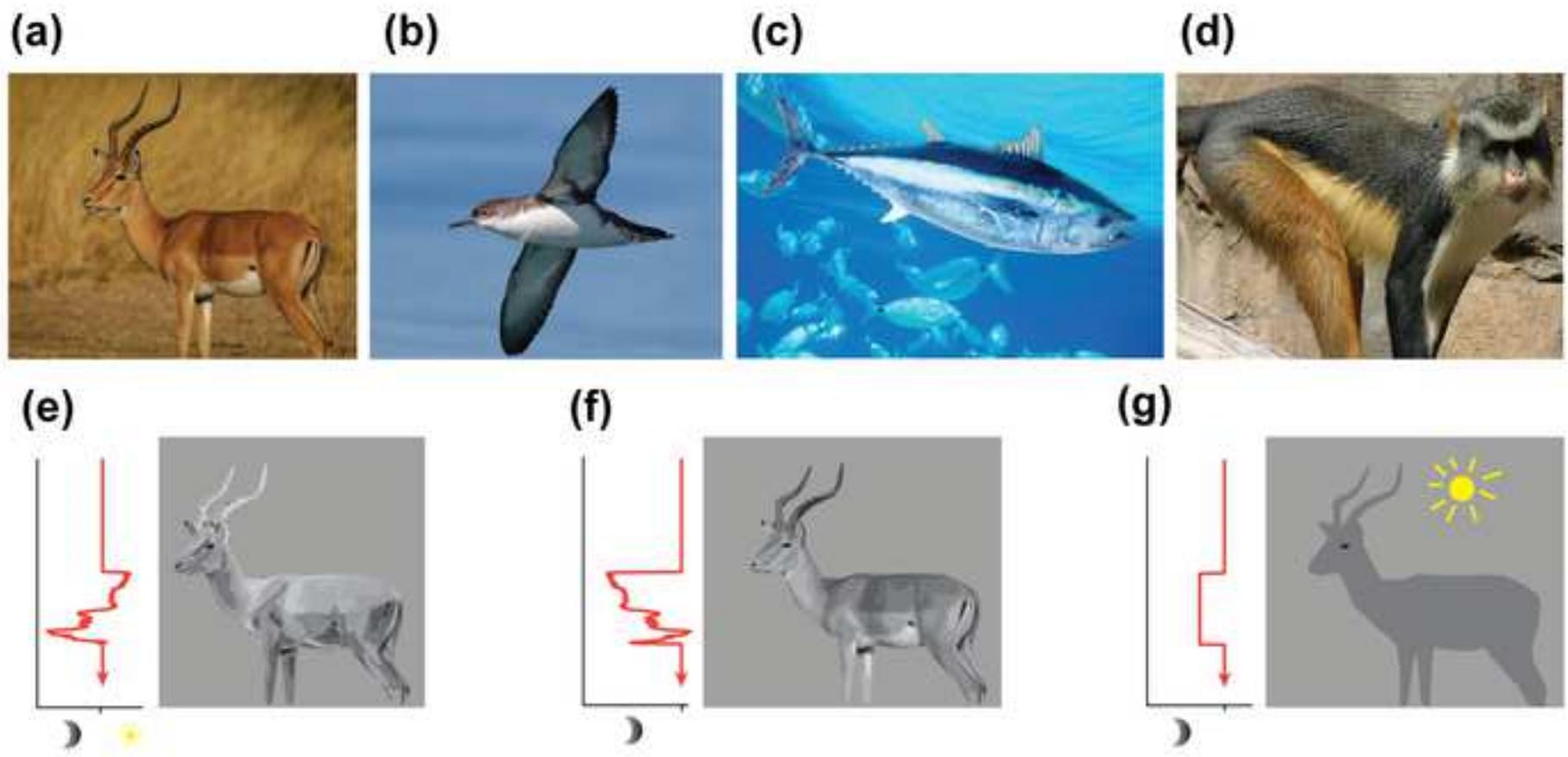
229 **Fig. 1. Colouration that is proposed to remove depth information.** Countershading colouration is  
230 one of the commonest forms of colouration, observed in animals such as mountain gazelle (**a**:  
231 *Gazella gazelle*), Manx shearwater (**b**: *Puffinus puffinus*), bluefin tuna (**c**: *Thunnus thynnus*) and  
232 Wolf's Mona monkey (**d**: *Ceropithecus wolfi*). Countershading is thought to enhance camouflage  
233 by reducing or eliminating self-shadows. When lit from overhead, objects such as a mountain  
234 gazelle produce a self-shadow on the underside of the body (**e**). Countershaded patterns (**f**)  
235 reverse this effect, increasing camouflage by reducing contrast and/or removing 3D shape cues (**g**).  
236 The plots (red lines in e-g) show changes in luminance across the body (dorsal to ventral  
237 direction); the x-axis indicates whether the body's luminance is darker (moon image) or brighter  
238 (sun image) than the background. Image sources: a: [www.pexels.com](http://www.pexels.com) (Harvey Sapir); b:  
239 [www.hubpages.com](http://www.hubpages.com); c: [www.stock.adobe.com](http://www.stock.adobe.com); d: [www.wikipedia.org](http://www.wikipedia.org).

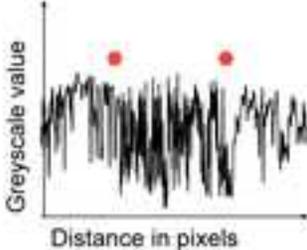
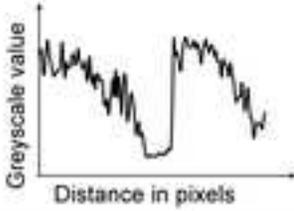
240

241 **Fig. 2. Other camouflage strategies that may interfere with depth perception.** a) The wing  
242 patterns of the geometrid moth *Alcis repandata* (**a**) produce a similar luminance profile to the  
243 background (plot shows changes in greyscale value across a transect (red dotted line in image), the  
244 red asterisks denote the wing edges). The wing patterning resembles the changes in luminance  
245 produced by the background relief, preventing prey detection by defeating the edge detectors and  
246 preventing image segregation. The cuttlefish *Sepia officinalis* (**b**) displays a unique disruptive  
247 pattern when placed on a 3D background, which may produce a percept of depth. Cuttlefish may  
248 therefore exploit predators' ability to recover depth from pictorial cues to prevent image  
249 segregation. The flat wings of the moth *Uropyia meticulodina* (**c**) have patterns that produce  
250 changes in luminance that are associated with sloped surfaces and edges (plot shows changes in  
251 greyscale across the transect marked by the red dashed line in the image). This patterning exploits  
252 depth cues such as shading and texture to facilitate misidentification. Geometrid moth (Mottled  
253 Umber, *Erannis defolaria*; **d**) with patterns that may alter the perceived depth of parts of the wing  
254 surface. These false edges mimic the changes in luminance that are associated with an object's  
255 boundaries and/or may generate illusory depth, causing incorrect boundary resolution and  
256 incorrect segregation. Image sources: a & d: [www.stock.adobe.com](http://www.stock.adobe.com); b: kindly provided by Sarah  
257 Zylinski; c: Shipher Wu (CC-BY-SA 2.0).

258

259



Camouflage strategy	Visual signal/percept	Mechanisms exploited	Outcome
<p><b>(a) Background matching (luminance profile)</b></p>  	<p>Edge detectors defeated</p> <p>Luminance profile matches background relief</p>		
<p><b>(b) Background matching (3D percept)</b></p>  	<p>Pictorial depth cues generate false surface contours and shading correspondences</p> <p>Illusory depth on body surface</p> <p>Incorrect boundary resolution and image segregation</p>		
<p><b>(c) Masquerade</b></p>  	<p>False edges stimulate edge detectors</p> <p>Pictorial depth cues used to generate false texture and relief</p> <p>Incorrect boundary resolution promotes object mis-identification</p> <p>Luminance gradient resembles surface of object being mimicked</p>		
<p><b>(d) Surface disruption</b></p>  	<p>Enhanced edges stimulate edge detectors</p> <p>Enhanced edges simulate changes in surface depth</p> <p>Incorrect boundary resolution</p> <p>Breaks up body surfaces into additional depth planes, causing incorrect segregation</p>		